

*Operational axioms
for Quantum Mechanics*

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On experimental science

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Since necessarily we work with only partial prior knowledge of both system and experimental apparatus, the rules for the experiment must be given in a probabilistic setting.

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The interaction between object and apparatus produces one of a **set of possible transformations** of the object, each one occurring with some probability.

Postulates

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- **Postulate 1 (Independent systems)** *There exist **independent** systems.*
- **Postulate 2 (Informationally complete observable)** *For each physical system there exists an **informationally complete observable** (Hardy, Fuchs).*
- **Postulate 3 (Local observability principle)** *For every composite system there exist informationally complete observables made only of **local** informationally complete observables.*
- **Postulate 4 (Informationally complete discriminating observable)** *For every system there exists a minimal informationally complete observable that can be achieved using a joint **discriminating observable** on the system + an “ancilla” .*
- **Postulate 5 (Symmetric faithful state)** *For every composite system made of two identical physical systems there exist a **symmetric joint state** that is both **dynamically** and **preparationally faithful**.*

Actions and outcomes

Experiment (or “action”): every experiment is described by a set $\mathbb{A} \equiv \{\mathcal{A}_j\}$ of possible transformations \mathcal{A}_j having overall unit probability, with the apparatus signaling the outcome j labeling which transformation actually occurred.

States

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State: A state ω for a physical system is a rule which provides the probability for any possible transformation within an experiment, namely:

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Identity transformation:
$$\omega(\mathcal{I}) = 1$$

Convex structure of states

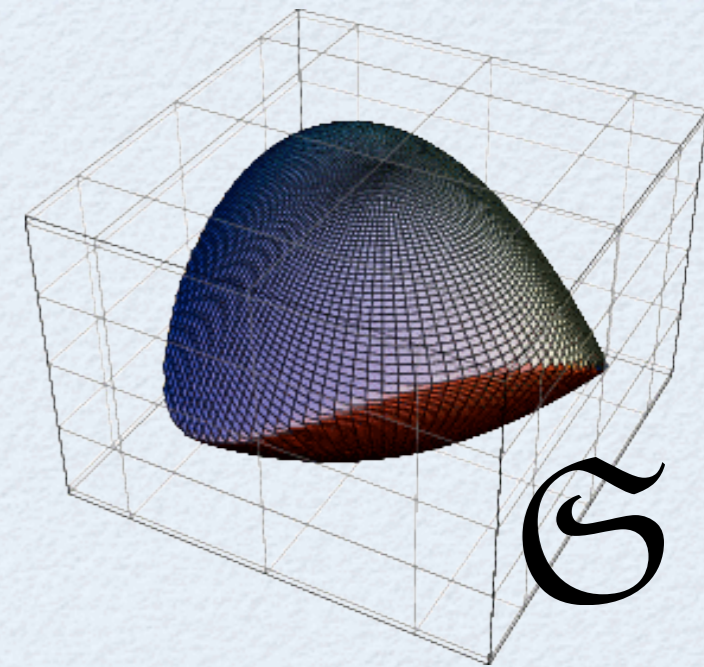
The possible states of a physical system make a convex set \mathcal{S}

ω_1, ω_2 any two states:

$$\omega = \lambda\omega_1 + (1 - \lambda)\omega_2, \quad 0 \leq \lambda \leq 1,$$

corresponding to the probability rule

$$\omega(\mathcal{A}) = \lambda\omega_1(\mathcal{A}) + (1 - \lambda)\omega_2(\mathcal{A})$$



Monoid of transformations

Transformations make a monoid: the composition $\mathcal{A} \circ \mathcal{B}$ of two transformations \mathcal{A} and \mathcal{B} is itself a transformation. Consistency of composition of transformations requires associativity, namely

$$\mathcal{C} \circ (\mathcal{B} \circ \mathcal{A}) = (\mathcal{C} \circ \mathcal{B}) \circ \mathcal{A}$$

There exists the identical transformation \mathcal{I} which leaves the physical system invariant, and which for every transformation \mathcal{A} satisfies the composition rule

$$\mathcal{I} \circ \mathcal{A} = \mathcal{A} \circ \mathcal{I} = \mathcal{A}$$

Independent systems and local transformations

Independent systems and local experiments: two physical systems are “independent” if on each system it is possible to perform “local experiments” for which on every joint state one has the commutativity of the pertaining transformations

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Multipartite system: a collection of independent systems

Local state

For a multipartite system we define the local state $\omega|_n$ of the n -th system the state that gives the probability of any local transformation \mathcal{A} on the n -th system with all other systems untouched, namely

$$\omega|_n(\mathcal{A}) \doteq \Omega(\mathcal{I}, \dots, \mathcal{I}, \underbrace{\mathcal{A}}_{nth}, \mathcal{I}, \dots)$$

Conditional state

When composing two transformations \mathcal{A} and \mathcal{B} the probability that \mathcal{B} occurs conditioned that \mathcal{A} occurred before is given by the **Bayes rule**

$$p(\mathcal{B}|\mathcal{A}) = \frac{\omega(\mathcal{B} \circ \mathcal{A})}{\omega(\mathcal{A})}$$

Conditional state: the conditional state $\omega_{\mathcal{A}}$ gives the probability that a transformation \mathcal{B} occurs on the physical system in the state ω after the transformation \mathcal{A} occurred, namely

$$\omega_{\mathcal{A}}(\mathcal{B}) \doteq \frac{\omega(\mathcal{B} \circ \mathcal{A})}{\omega(\mathcal{A})}$$

Weights and Operations

Weight: un-normalized state

$$\omega = \frac{\tilde{\omega}}{\tilde{\omega}(\mathcal{I})}$$

$$0 \leq \tilde{\omega}(\mathcal{A}) \leq \tilde{\omega}(\mathcal{I}) < +\infty$$

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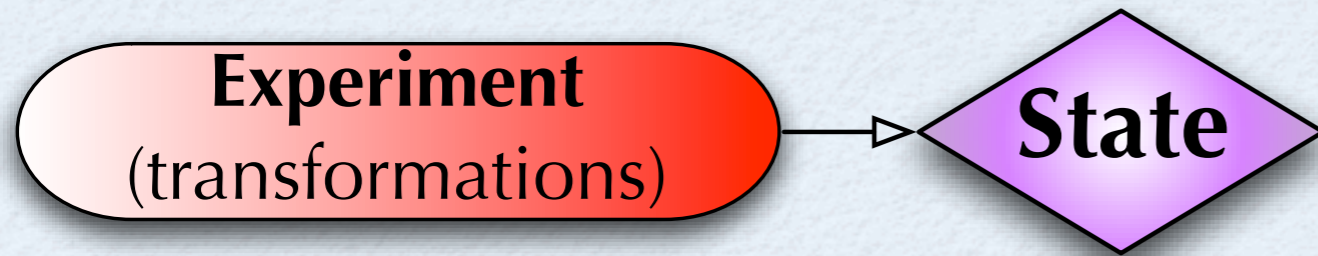
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Evolution as conditioning

Axioms

Theorems

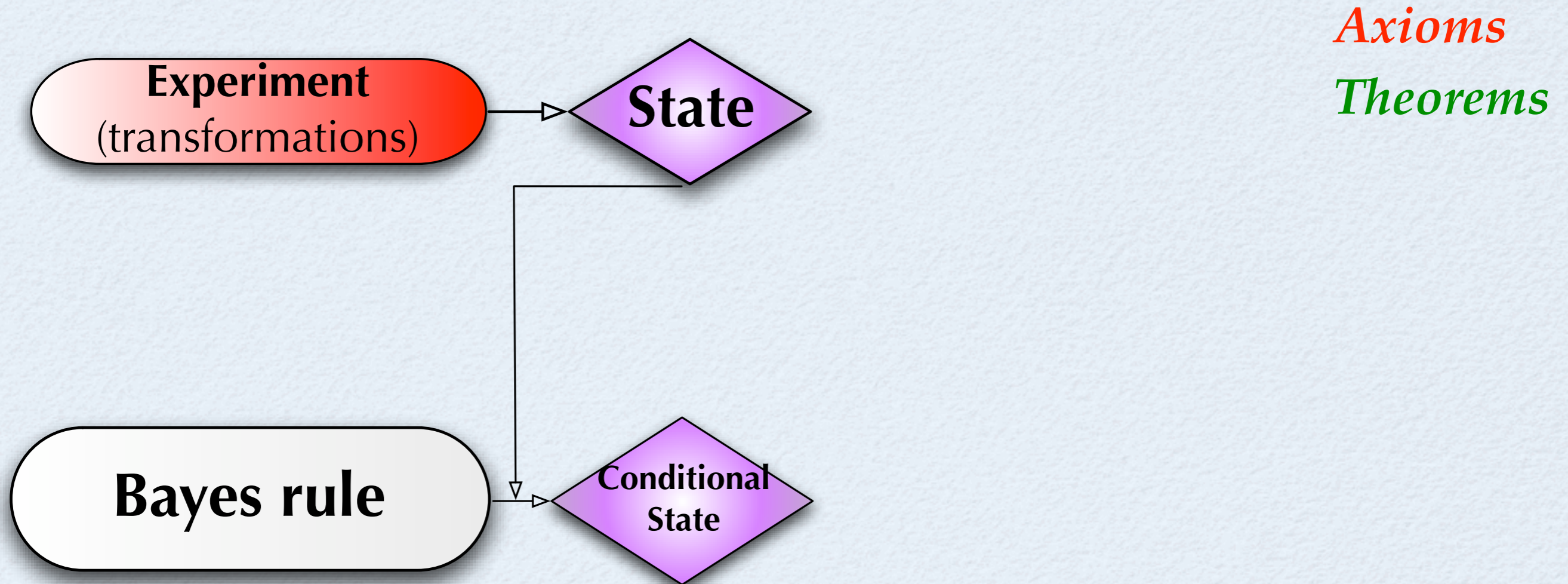
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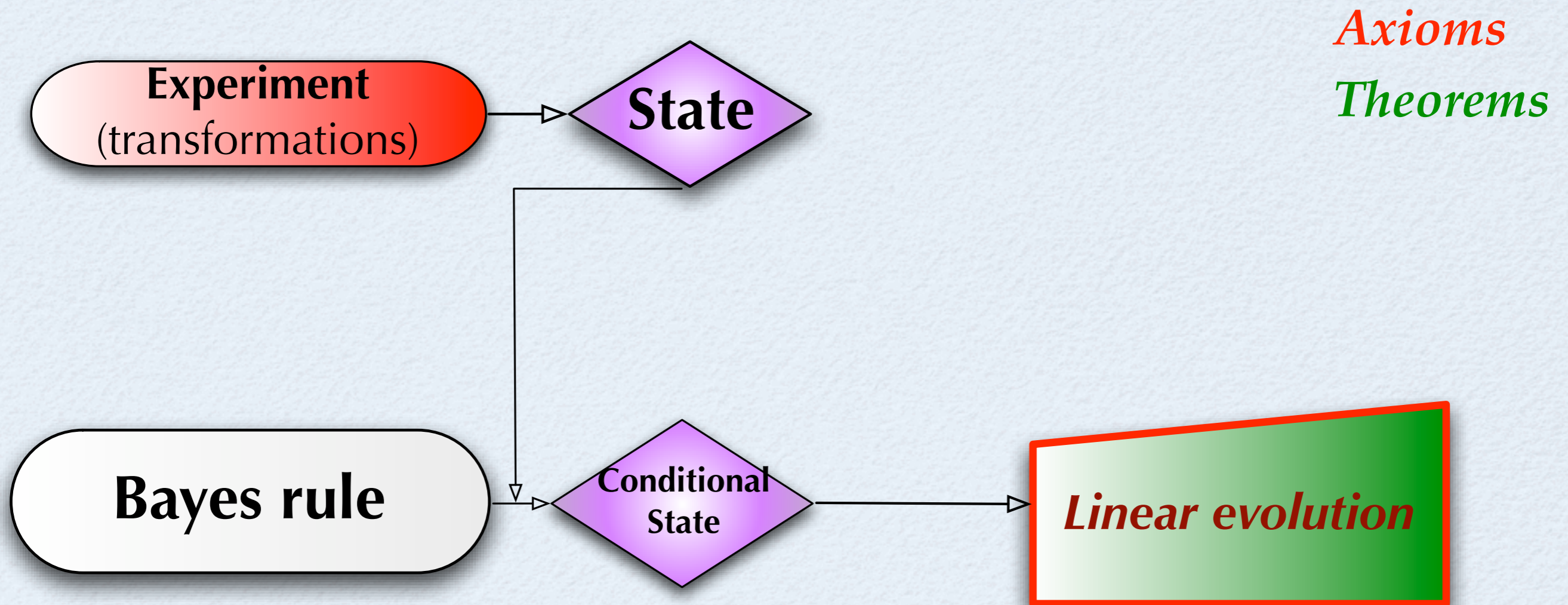
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A transformation is completely specified by the two classes

Addition of transformations

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$$\forall \omega \in \mathfrak{S} \quad \omega(\mathcal{A}_1 + \mathcal{A}_2) = \omega(\mathcal{A}_1) + \omega(\mathcal{A}_2) \quad (\text{info-class})$$

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$\circ, +$ distributive

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acausality of local actions: any local action on a system is equivalent to the identity transformation on another independent system.

$$\mathcal{I}(\mathbb{A}) := \sum_{\mathcal{A}_j \in \mathbb{A}} \mathcal{A}_j$$

$$\forall \Omega \in \mathcal{S}^{\times 2}, \forall \mathbb{A}, \quad \Omega_{\mathcal{I}(\mathbb{A}), \mathcal{I}}|_2 = \Omega|_2$$

No-signaling

Theorem 2 (No signaling, i. e. acausality of local actions) *Any local "action" (i. e. experiment) on a system does not affect another independent system. More precisely, any local action on a system is equivalent to the identity transformation when viewed from another independent system. In equations one has*

$$\forall \Omega \in \mathfrak{G}^{\times 2}, \forall \mathbb{A}, \quad \Omega_{\mathcal{I}(\mathbb{A}), \mathcal{I}}|_2 = \Omega|_2. \quad (25)$$

Proof. By definition, for $\mathcal{B} \in \mathfrak{T}$ one has $\Omega|_2(\mathcal{B}) = \Omega(\mathcal{I}, \mathcal{B})$, and using Eq. (24) according to Rule 4 one has

$$\Omega(\mathcal{I}(\mathbb{A}), \mathcal{B}) = \sum_{\mathcal{A}_j \in \mathbb{A}} \Omega(\mathcal{A}_j, \mathcal{B}) = \Omega(\mathcal{I}, \mathcal{B}) =: \Omega|_2(\mathcal{B}). \quad (26)$$

On the other hand, we have

$$\Omega_{\mathcal{I}(\mathbb{A}), \mathcal{I}}|_2(\mathcal{B}) = \Omega((\mathcal{I}, \mathcal{B}) \circ (\mathcal{I}(\mathbb{A}), \mathcal{I})) = \Omega(\mathcal{I}(\mathbb{A}), \mathcal{B}), \quad (27)$$

namely the statement. ■

Notice the consistency with Rule 4:

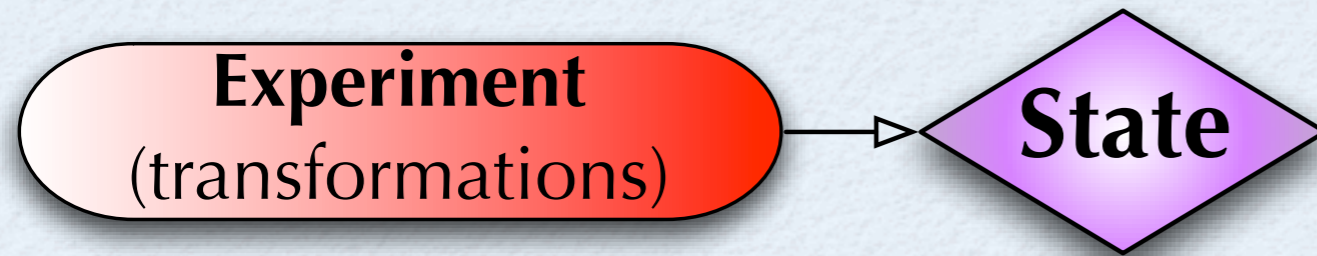
$$\begin{aligned} \Omega_{\mathcal{I}(\mathbb{A}), \mathcal{I}}|_2(\mathcal{B}) &= \Omega_{\mathcal{I}(\mathbb{A}), \mathcal{I}}(\mathcal{I}, \mathcal{B}) = \sum_{\mathcal{A}_j \in \mathbb{A}} \Omega_{\mathcal{A}_j, \mathcal{I}}(\mathcal{I}, \mathcal{B}) \frac{\Omega(\mathcal{A}_j, \mathcal{I})}{\sum_{\mathcal{A}_j \in \mathbb{A}} \Omega(\mathcal{A}_j, \mathcal{I})} \\ &= \sum_{\mathcal{A}_j \in \mathbb{A}} \frac{\Omega(\mathcal{A}_j, \mathcal{B})}{\Omega(\mathcal{A}_j, \mathcal{I})} \frac{\Omega(\mathcal{A}_j, \mathcal{I})}{\Omega(\mathcal{I}, \mathcal{I})} = \sum_{\mathcal{A}_j \in \mathbb{A}} \Omega(\mathcal{A}_j, \mathcal{B}) = \Omega(\mathcal{I}, \mathcal{B}). \end{aligned} \quad (28)$$

No-signaling from dynamical independence

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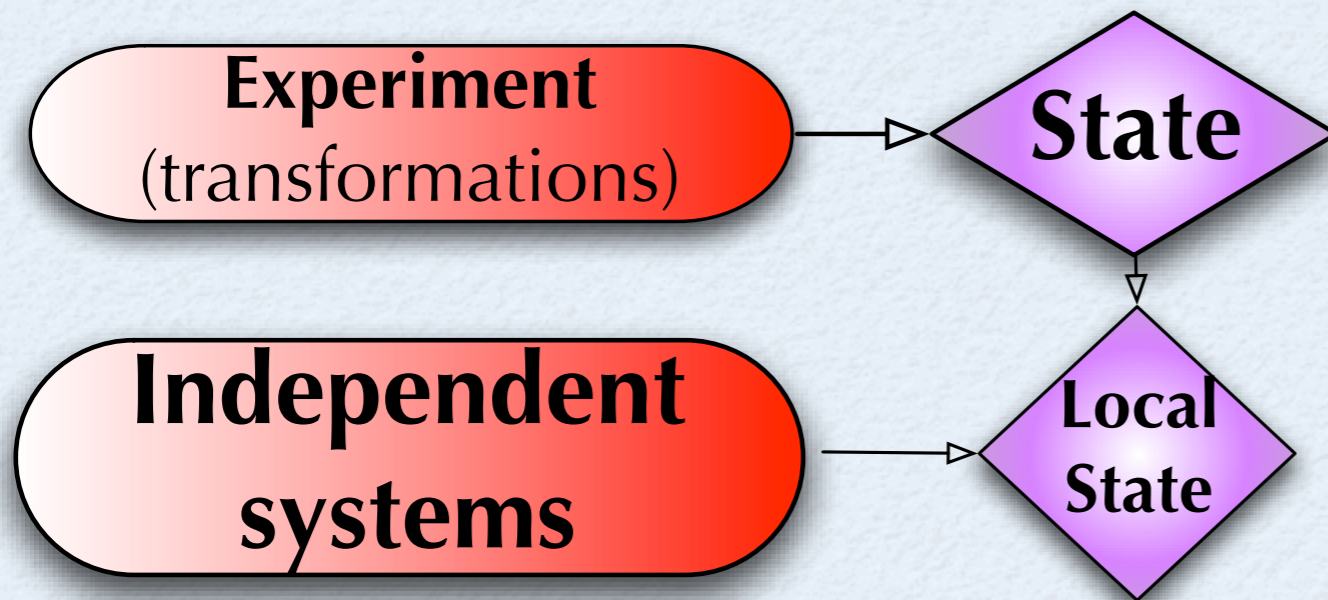
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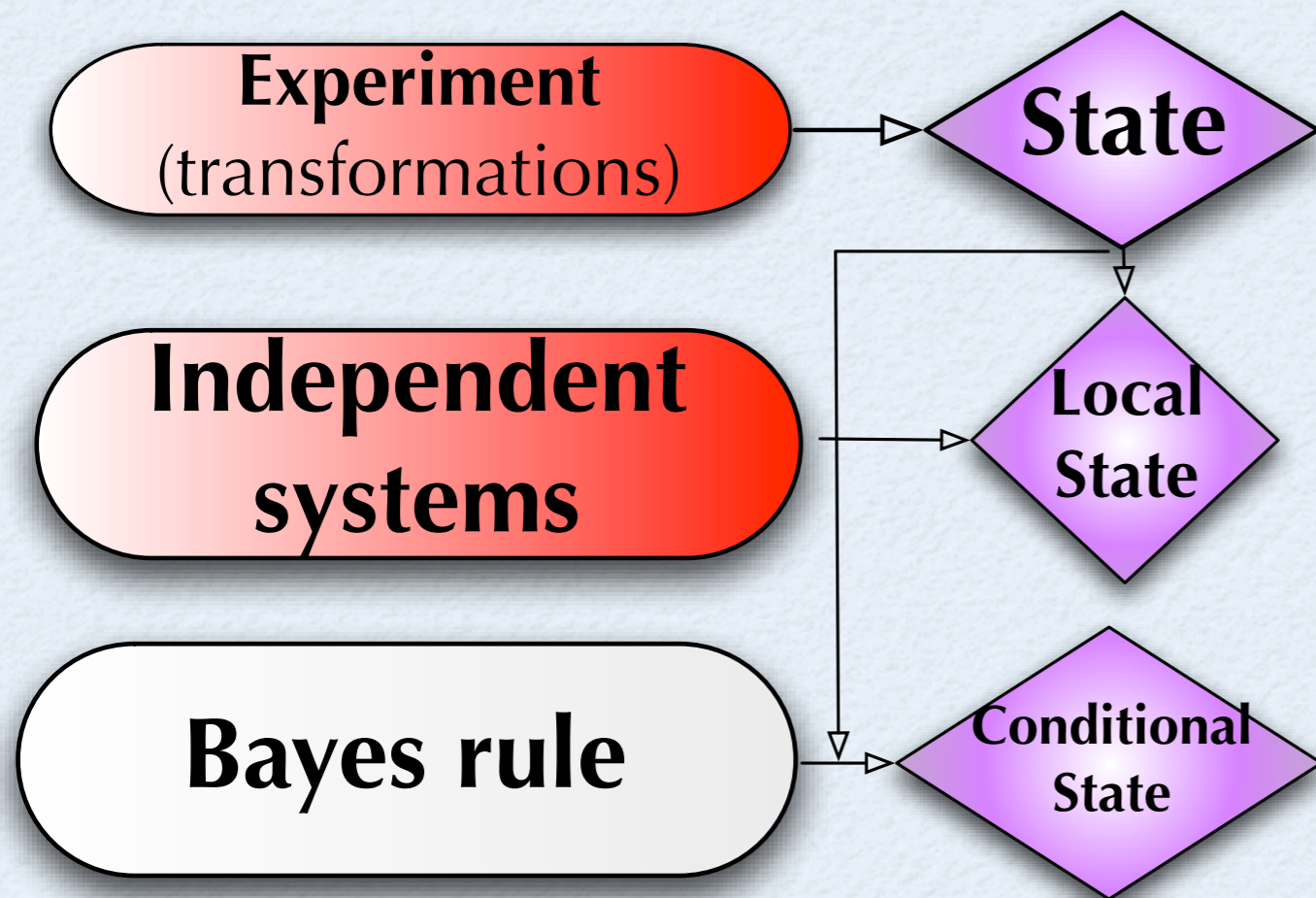
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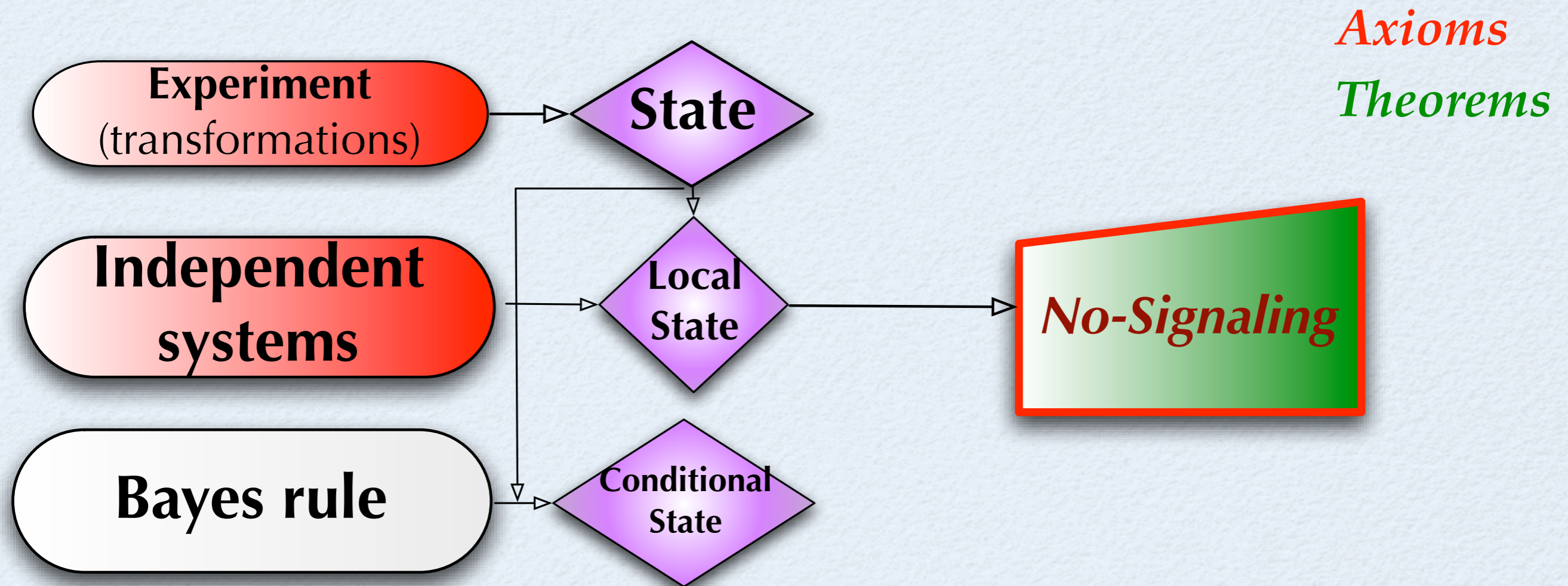
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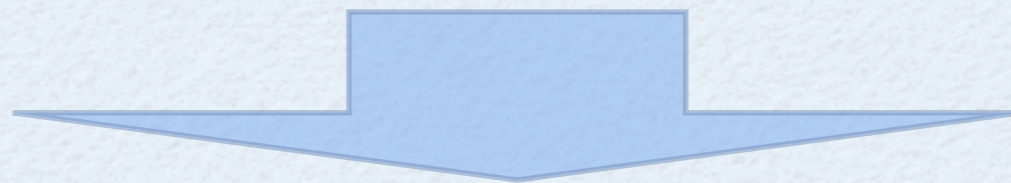


Informational compatibility

Multiplication by a scalar: for each transformation \mathcal{A} the transformation $\lambda\mathcal{A}$ for $0 \leq \lambda \leq 1$ is defined as the transformation which is dynamically equivalent to \mathcal{A} but occurs with probability $\omega(\lambda\mathcal{A}) = \lambda\omega(\mathcal{A})$

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***Convex structure for transformations \mathcal{T}
and for actions***

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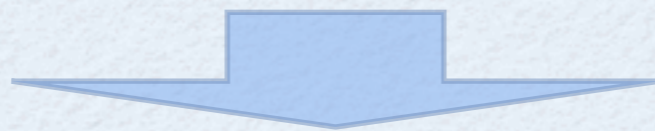
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duality



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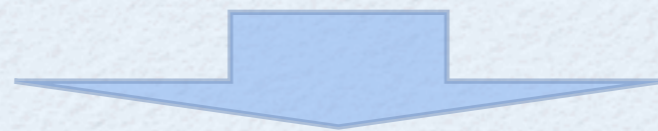
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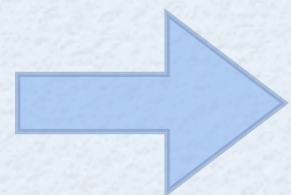
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Generalized weights, transformations, and effects

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$\mathfrak{T}_{\mathbb{R}}$ *Banach algebra*

Banach-space structures

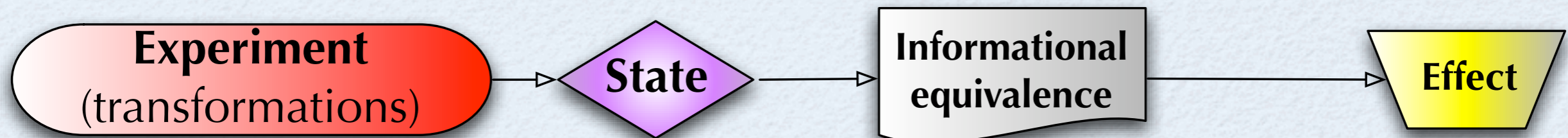
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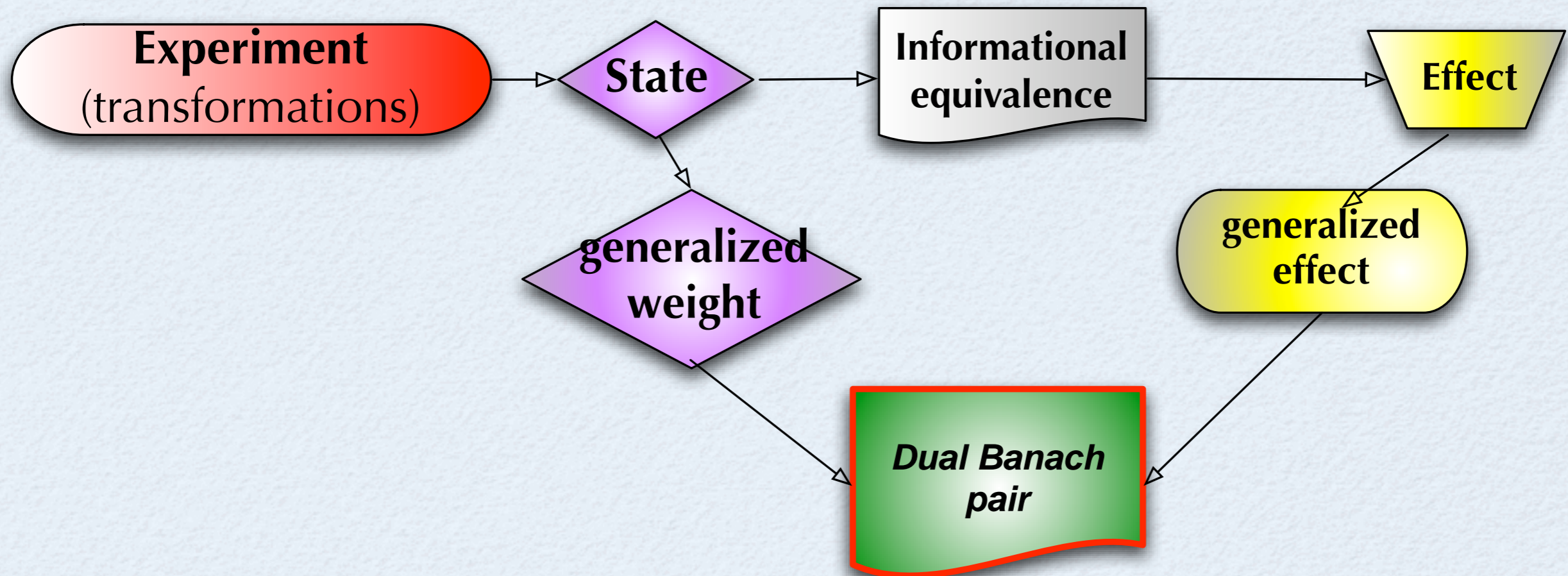
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Banach-space structures

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Observable

Observable: the complete set of effects $\{l_j\}$ of an experiment $\mathbb{A} = \{\mathcal{A}_j\}$, namely $l_j = \underline{\mathcal{A}_j} \quad \forall j$

Informationally complete observable

Informationally complete observable: an observable $\mathbb{L} = \{l_i\}$ is informationally complete if any effect l can be written as linear combination of elements of \mathbb{L} , namely there exist coefficients $c_i(l)$ such that

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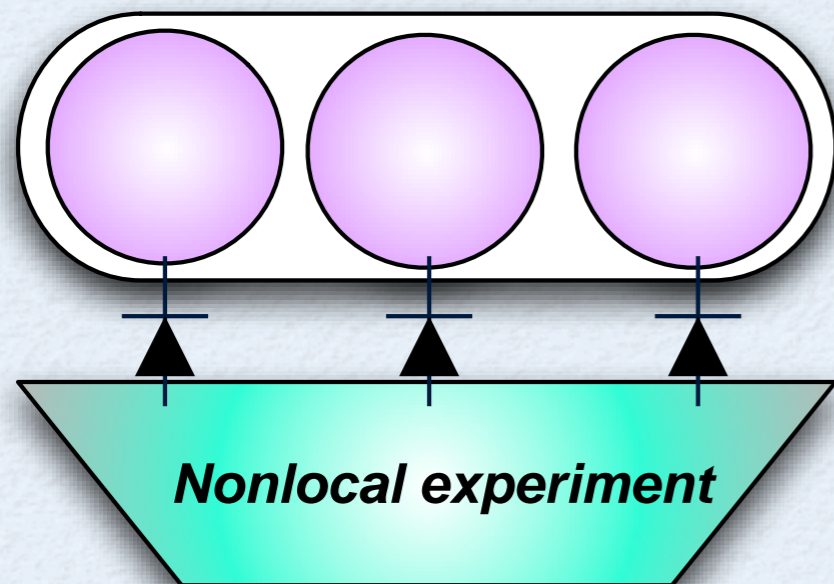
affine dimension: $\dim(\mathfrak{S}) = |\mathbb{L}| - 1$, for \mathbb{L} minimal informationally complete on \mathfrak{S}

Postulate 3: Local observability principle

For every composite system there exist informationally complete observables made only of local informationally complete observables.

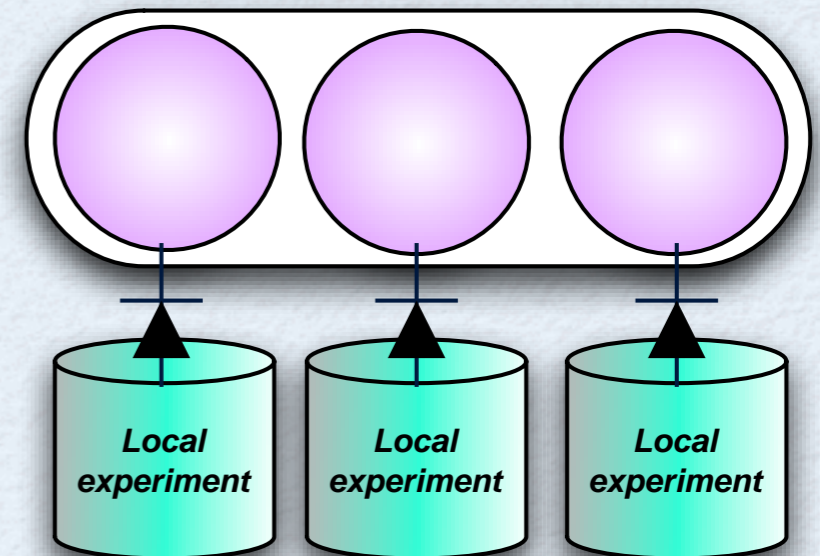
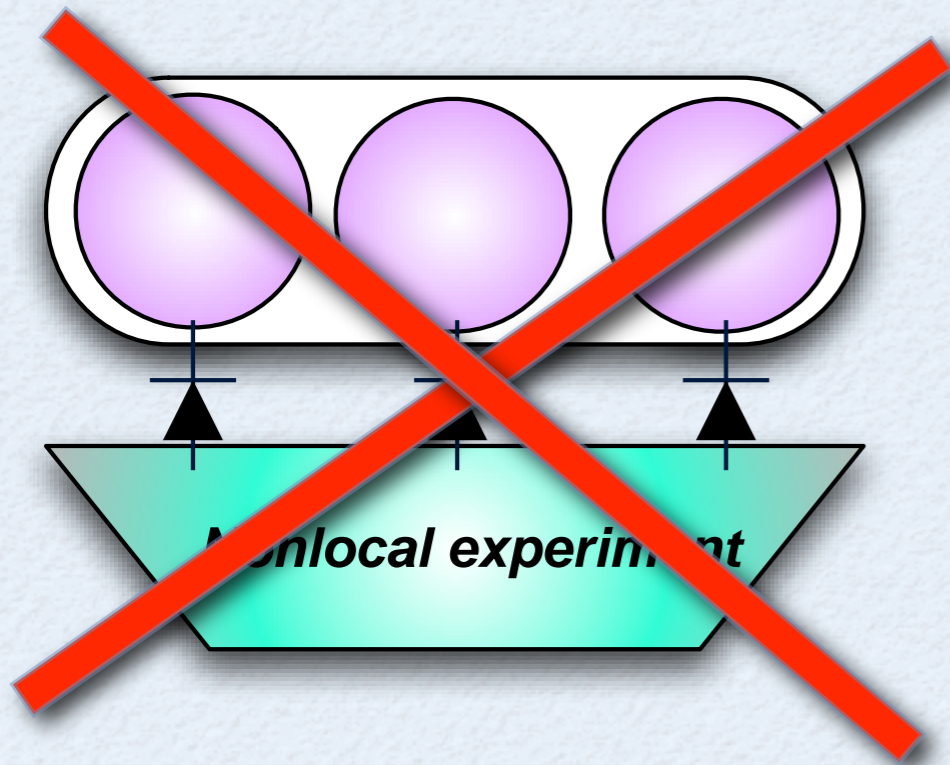
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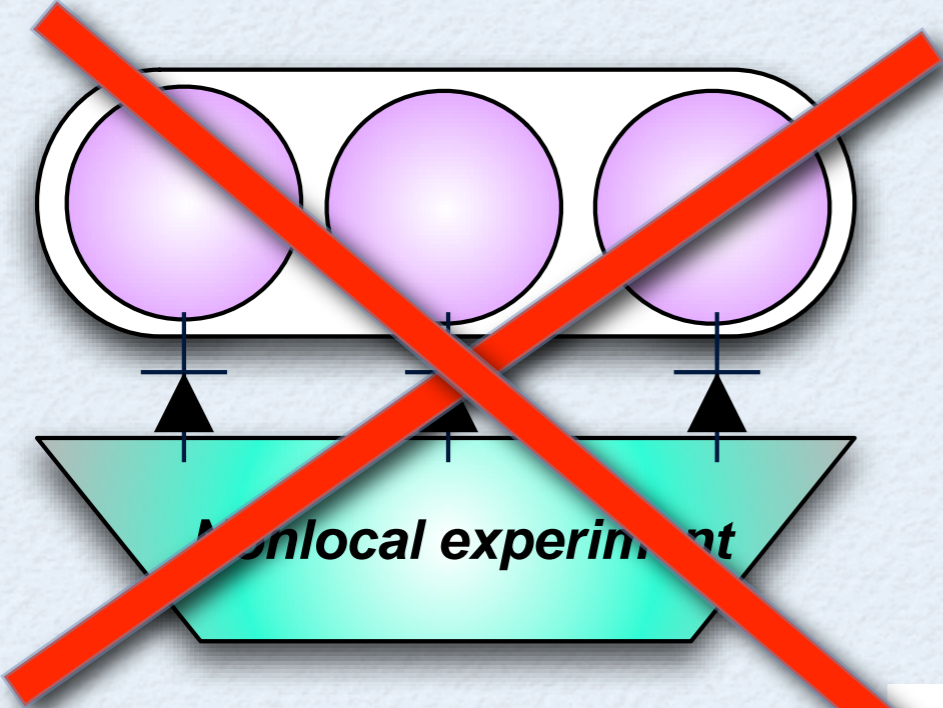
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Postulate 3: Local observability principle

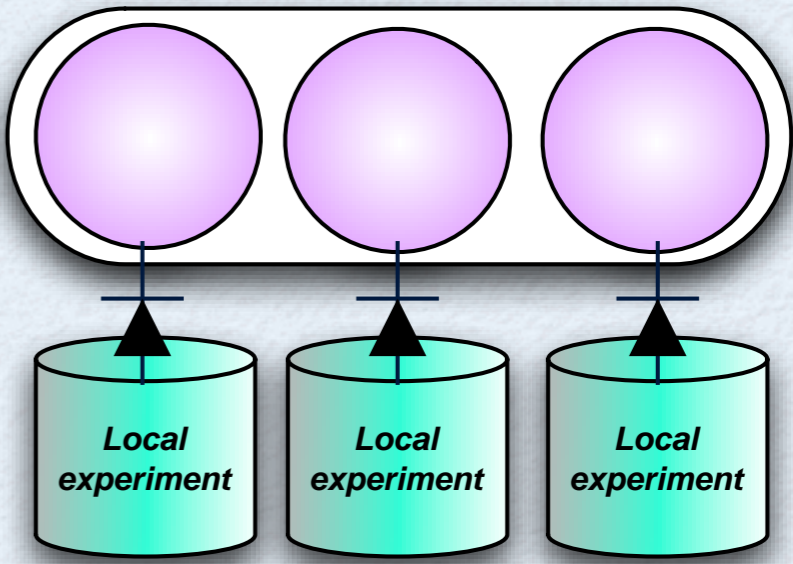
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Holism

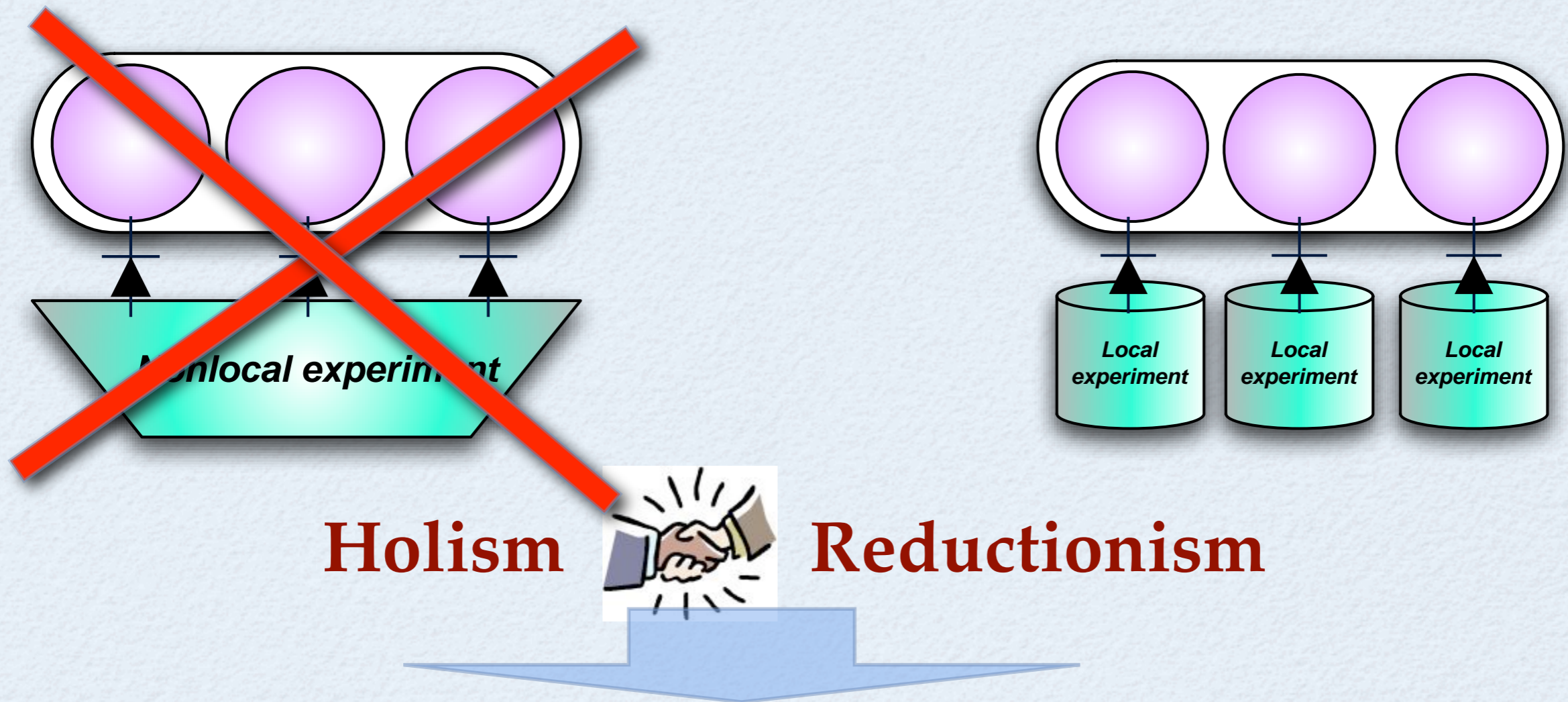


Reductionism



Postulate 3: Local observability principle

For every composite system there exist informationally complete observables made only of local informationally complete observables.



identity for the affine dimension of composite systems

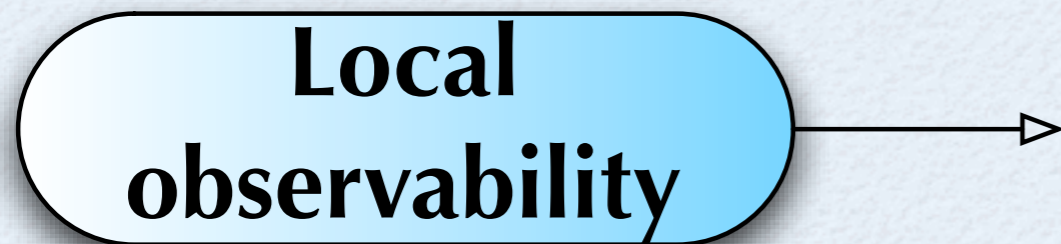
$$\dim(\mathfrak{S}_{12}) = \dim(\mathfrak{S}_1) \dim(\mathfrak{S}_2) + \dim(\mathfrak{S}_1) + \dim(\mathfrak{S}_2)$$

Postulate 3: Local observability principle

Postulates

Axioms

Theorems



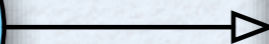
Postulate 3: Local observability principle

Postulates

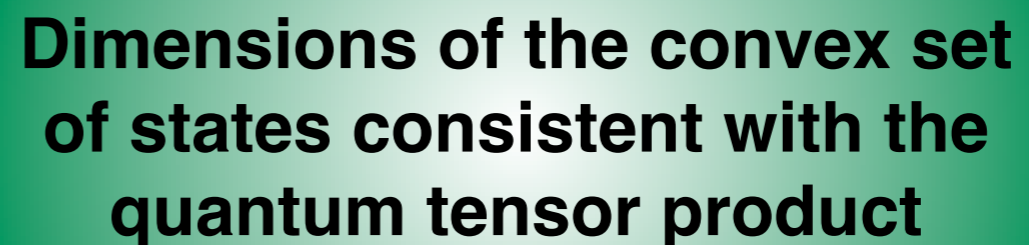
Axioms

Theorems

**Local
observability**



**Dimensions of the convex set
of states consistent with the
quantum tensor product**



Block representation

$$l_{\underline{\mathcal{A}}} = \sum_j m_j(\underline{\mathcal{A}}) n_j \quad l_{\underline{\mathcal{A}}}(\omega) = m(\underline{\mathcal{A}}) \cdot n(\omega) + q(\underline{\mathcal{A}})$$

Block representation

$$l_{\underline{\mathcal{A}}} = \sum_j m_j(\underline{\mathcal{A}}) n_j \quad l_{\underline{\mathcal{A}}}(\omega) = m(\underline{\mathcal{A}}) \cdot n(\omega) + q(\underline{\mathcal{A}})$$

**Conditioning:
fractional affine
transformation**

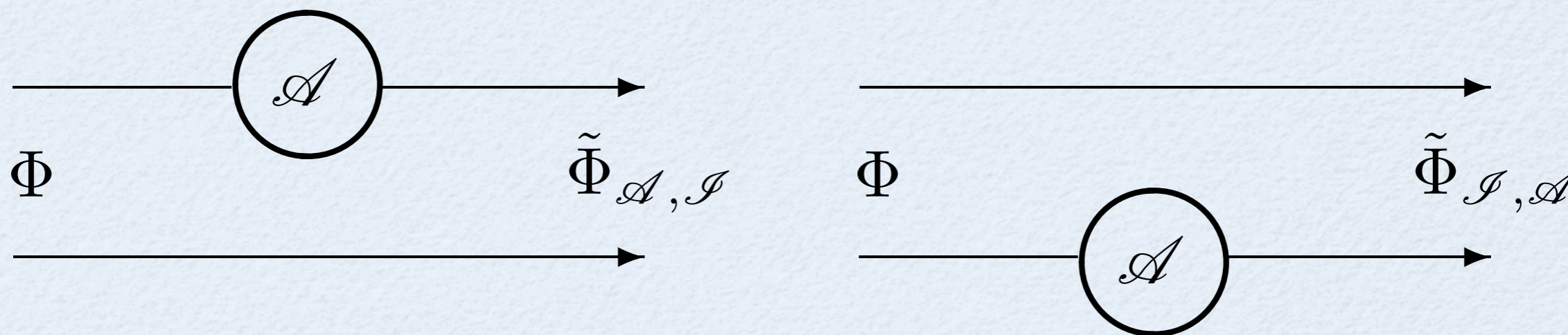
$$n(\omega) \longrightarrow n(\omega_{\mathcal{A}})$$

$$n(\omega_{\mathcal{A}}) = \frac{M(\mathcal{A})n(\omega) + \mathbf{k}(\mathcal{A})}{m(\underline{\mathcal{A}}) \cdot n(\omega) + q(\underline{\mathcal{A}})}$$

$$M_{ij}(\mathcal{A}) = \begin{pmatrix} q(\underline{\mathcal{A}}) & m(\underline{\mathcal{A}}) \\ \mathbf{k}(\mathcal{A}) & M(\mathcal{A}) \end{pmatrix}$$

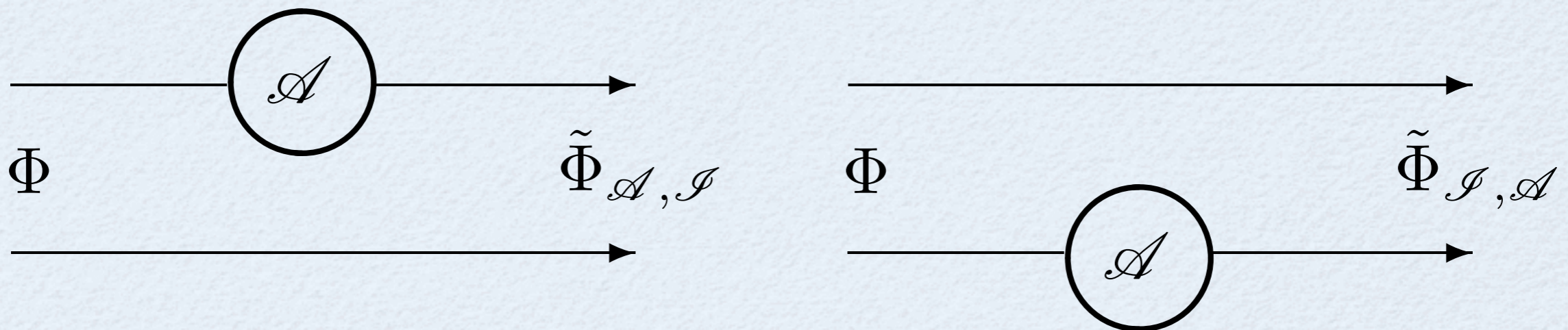
Faithful states

Dynamically faithful state: we say that a state Φ of a bipartite system is dynamically faithful if when acting on it with a local transformation \mathcal{A} on one system the output conditioned weight $\tilde{\Phi}_{\mathcal{A}, \mathcal{I}}$ is in 1-to-1 correspondence with the transformation \mathcal{A}



Faithful states

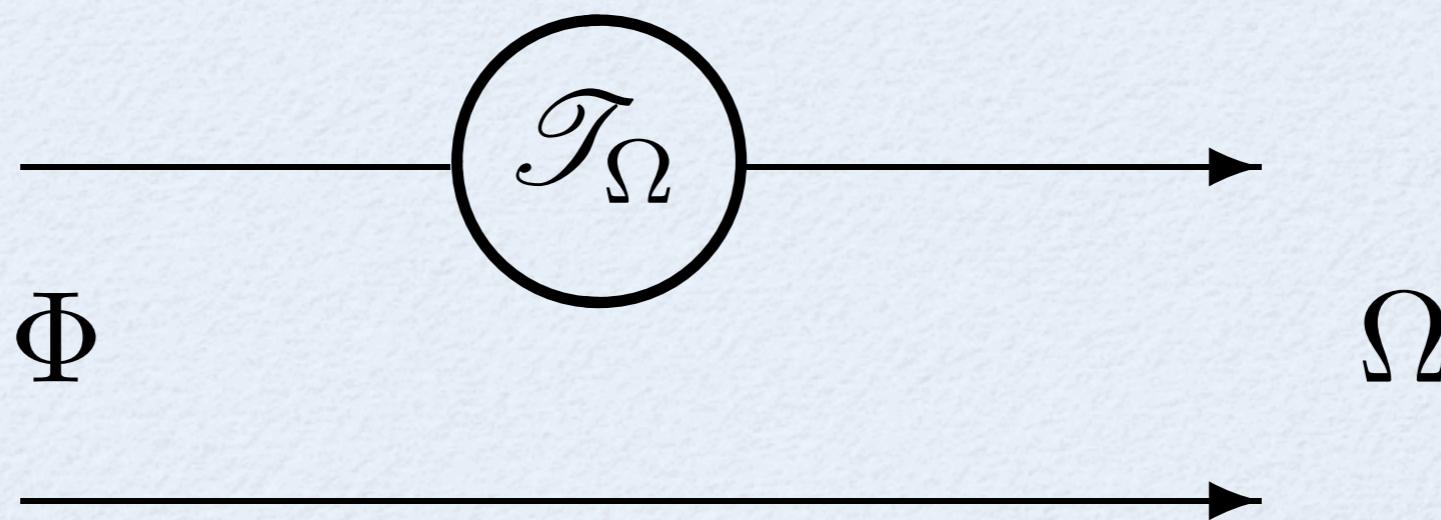
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$$(\mathcal{A}, \mathcal{I})\Phi = 0 \iff \mathcal{A} = 0$$

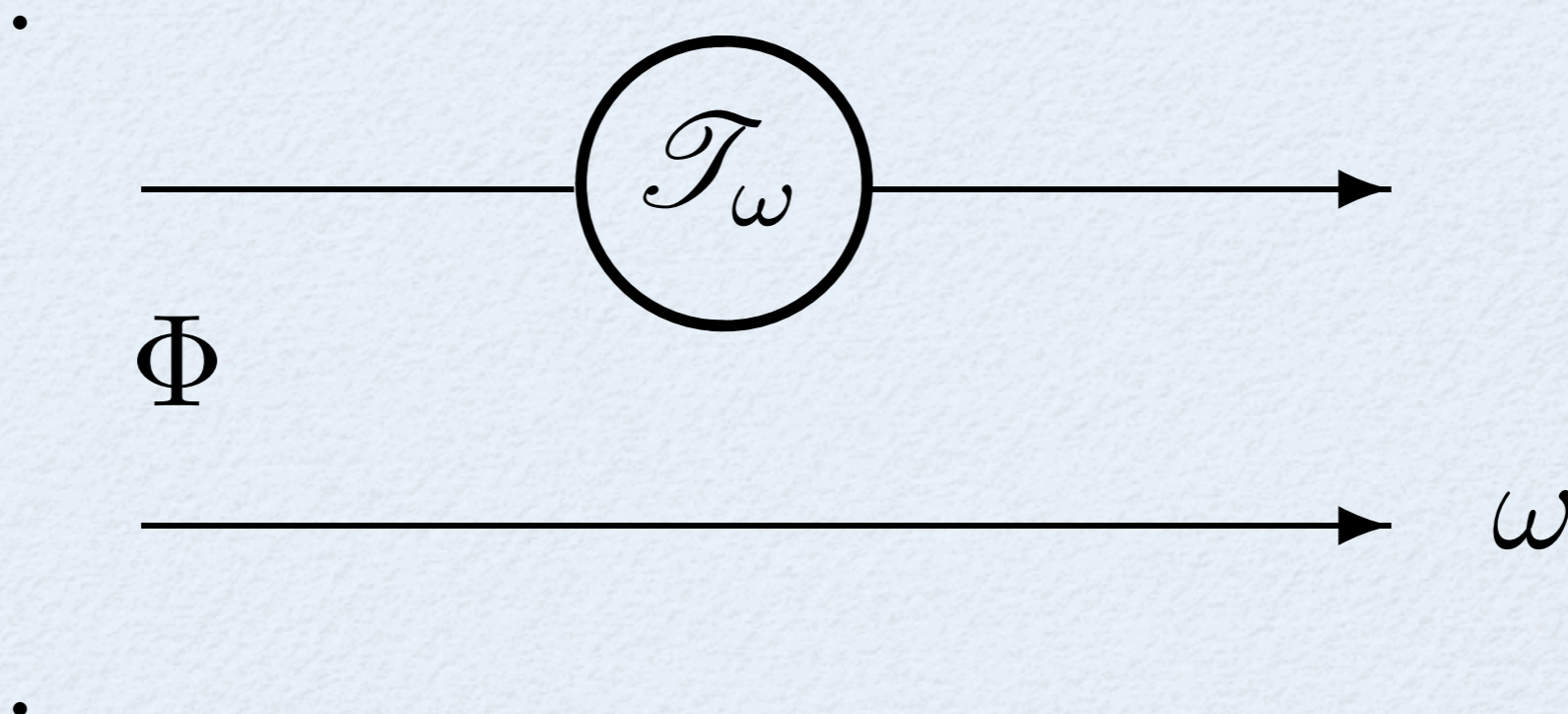
Faithful states

Preparationally faithful state: we say that a state Φ of a bipartite system is preparationally faithful if every joint states Ω can be achieved by a suitable local transformation \mathcal{T}_Ω on one system occurring with nonzero probability



Faithful states

Clearly a preparationally faithful state Φ of a bipartite system is also *locally* preparationally faithful, namely every local state ω of one component system can be achieved by a suitable local transformation \mathcal{T}_ω on the other component system



Faithful states

Symmetric bipartite state: we call a joint state Φ of a bipartite system symmetric if

$$\Phi(\mathcal{A}, \mathcal{B}) = \Phi(\mathcal{B}, \mathcal{A})$$

Perfectly discriminating observable

Perfectly discriminable states/observable $\{\omega_j\}$: there exists an observable $\mathbb{L} = \{l_i\}$ such that

$$l_i(\omega_j) = \delta_{ij}$$

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Informational dimension $\dim_{\#}(\mathfrak{S})$: maximal number of perfectly discriminable states

Postulate 4: Informationally complete discriminating observable

*For every system there exists a minimal informationally complete observable that can be achieved using a **joint discriminating observable** on the system + an “ancilla” (identical independent system).*

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Dimensionality identities

\implies		
P2 (infoc.)	$\dim(\mathfrak{P}_{\mathbb{R}}) = \dim(\mathfrak{S}) + 1$	(D2)
P3 (loc. obs.)	$\dim(\mathfrak{S}_{12}) = \dim(\mathfrak{S}_1) \dim(\mathfrak{S}_2) + \dim(\mathfrak{S}_1) + \dim(\mathfrak{S}_2)$	(D3)
P4 (infoc. discr.)	$\dim(\mathfrak{S}) = \dim_{\#}(\mathfrak{S}^{\times 2}) - 1$	(D5)
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$$\dim(\mathfrak{P}_{\mathbb{R}}) = \dim_{\#}(\mathfrak{S})^2$$

Dimensionality identities

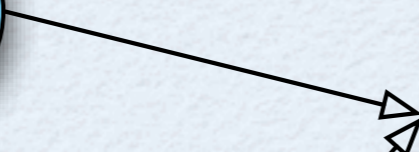
Postulates

Axioms

Theorems

**Local
observability**

*Info-complete from joint
discriminating observable*



Dimensionality identities

Postulates

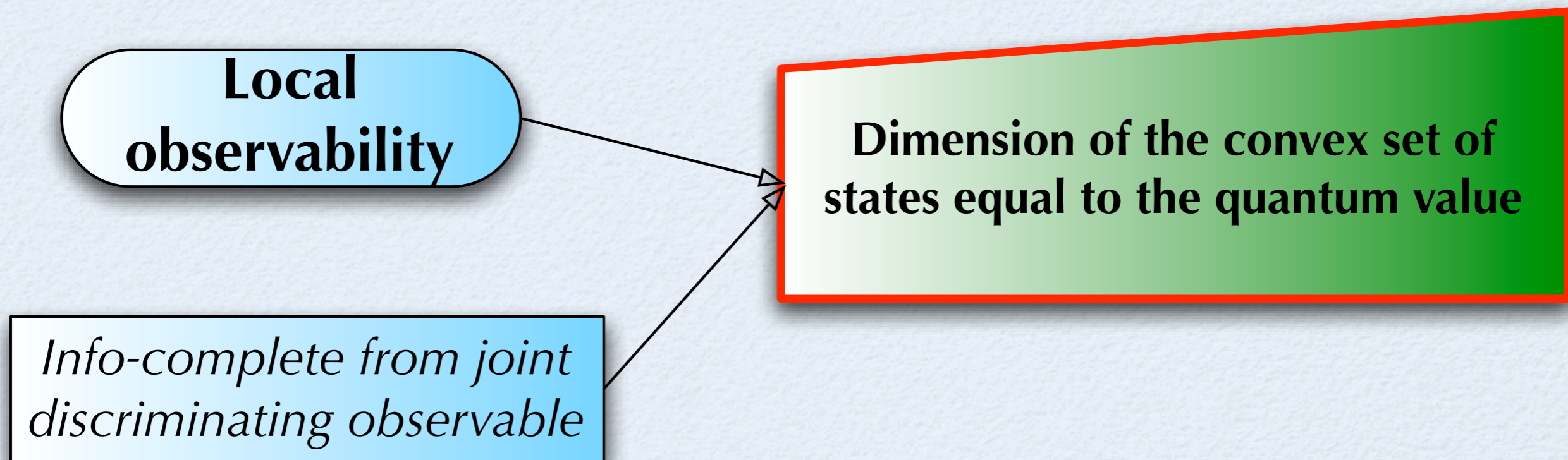
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**Local
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**Dimension of the convex set of
states equal to the quantum value**



Scalar product over effects

Using the symmetric dynamically faithful state one introduces a strictly positive real scalar product over effects $\mathfrak{P}_{\mathbb{R}}$

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$\mathfrak{P}_{\mathbb{R}}$ real (pre)Hilbert space of dimension $\dim_{\#}(\mathfrak{E})^2$

Positive bilinear form

Positive form over generalized effects: from Φ real symmetric form over effects obtain the positive form (via informationally complete observable)

$$|\Phi| := \Phi_+ - \Phi_-.$$

$$|\Phi|(\underline{\mathcal{A}}, \underline{\mathcal{B}}) = \Phi(\underline{\mathcal{A}}, \zeta(\underline{\mathcal{B}})), \quad \zeta(\underline{\mathcal{A}}) = (\mathcal{P}_+ - \mathcal{P}_-)(\underline{\mathcal{A}})$$
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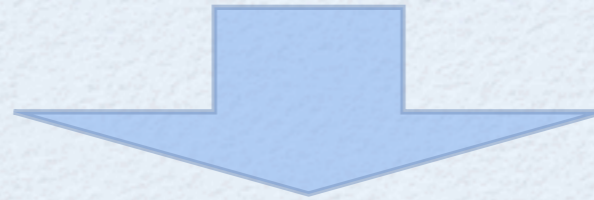
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The complex Hilbert space formulation



For finite dimensions the real Hilbert space $\mathfrak{P}_{\mathbb{R}}$ is isomorphic to the real Hilbert space of Hermitian complex matrices representing selfadjoint operators over a complex Hilbert space \mathbf{H} of dimensions $\dim(\mathbf{H}) = \dim_{\#}(\mathfrak{S})$.

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**This is the Hilbert space formulation
of Quantum Mechanics**

Positive bilinear form

If the state is also preparationally faithful then one can make every state correspond to an effect

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Then one can write the probability rule in terms of a real scalar product pairing between states and effects, with the convex cones of effects and states corresponding to the convex cone of positive matrices.

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This is the Quantum Mechanical *Born rule*

Positive bilinear form

Since Φ is *preparationally* faithful, then for every state ω there exists a suitable transformation \mathcal{I}_ω such that $\omega = \Phi_{\mathcal{I}, \mathcal{I}_\omega} |1$ with probability $\Phi(\mathcal{I}, \mathcal{I}_\omega) > 0$

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Then we can write the probability rule in terms of the pairing between states and effects:

$$\omega(\underline{\mathcal{C}}) = \Phi_{\mathcal{I}, \mathcal{I}_\omega} |1(\underline{\mathcal{C}}) = |\Phi|(\underline{\mathcal{C}}, \underline{\widetilde{\mathcal{I}}}_\omega),$$

$$\underline{\widetilde{\mathcal{I}}}_\omega = \frac{\zeta(\underline{\mathcal{I}}_\omega)}{\Phi(\underline{\mathcal{I}}, \underline{\mathcal{I}}_\omega)}$$

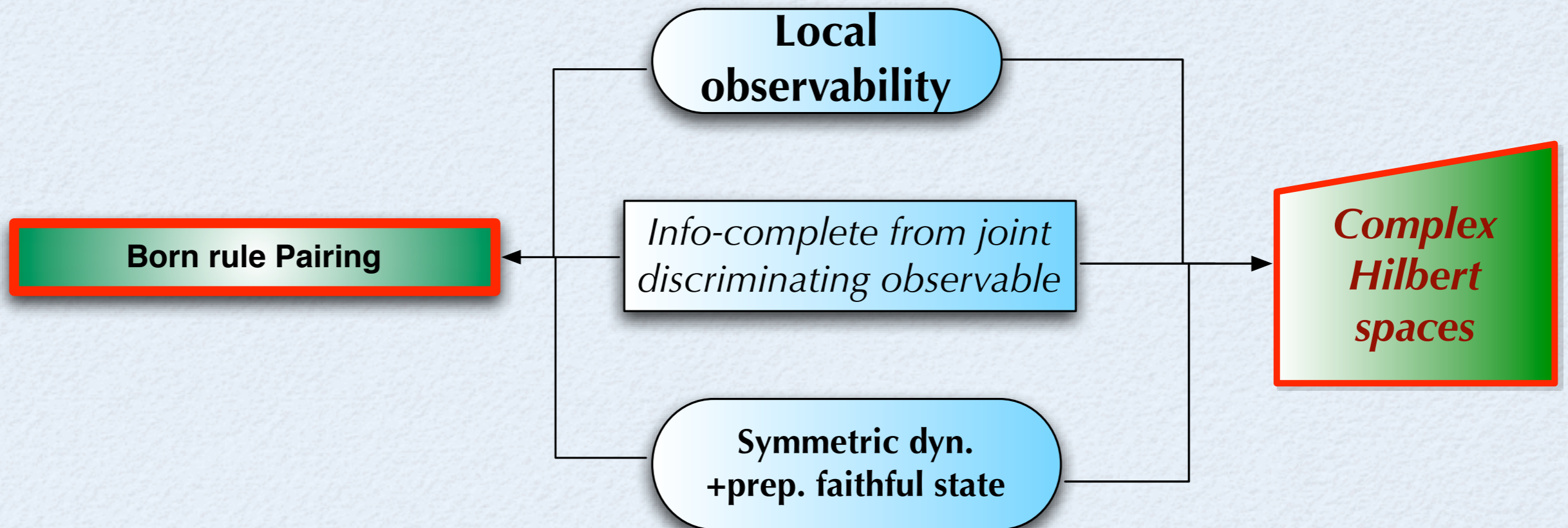
The complex Hilbert space formulation

**Local
observability**

*Info-complete from joint
discriminating observable*

**Symmetric dyn.
+prep. faithful state**

The complex Hilbert space formulation



The complex Hilbert space formulation

End of story:

The complex Hilbert space formulation

End of story:

- *construct complex operators by complex linear combination of effects*

The complex Hilbert space formulation

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The complex Hilbert space formulation

End of story:

- *construct complex operators by complex linear combination of effects*
- *physical transformations are described by CP trace-decreasing maps*
- *etc.*

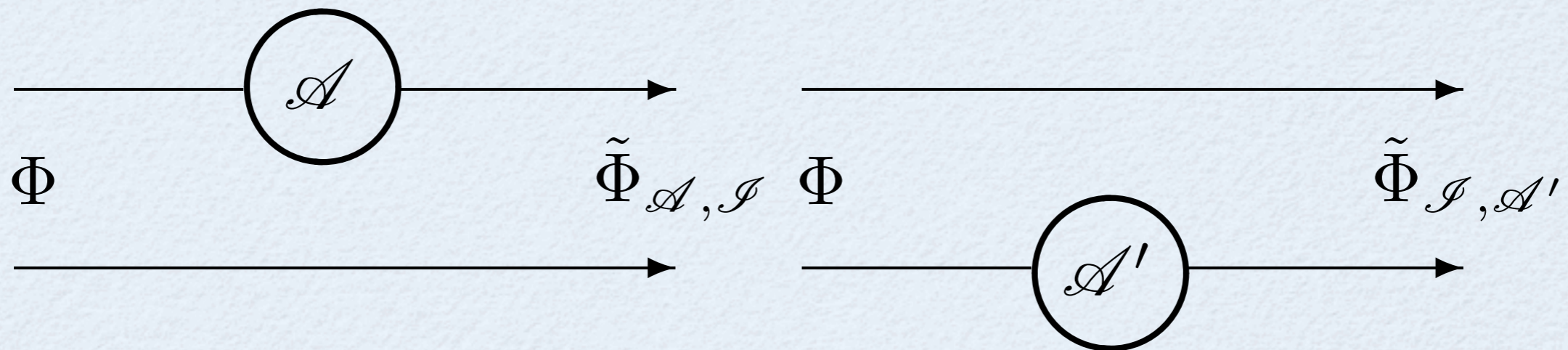
Operational definition of *transposed*

Existence of symmetric faithful states



“transposition” over the real algebra \mathcal{A} of (generalized) transformations

$$\mathcal{A} \iff \mathcal{A}'$$



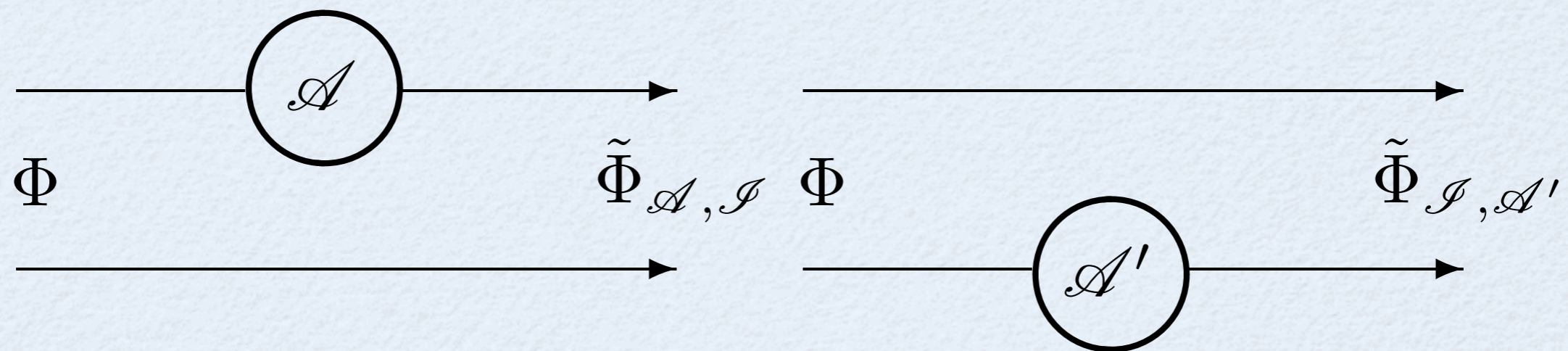
Operational definition of *transposed*

Existence of symmetric faithful states



“transposition” over the real algebra \mathcal{A} of (generalized) transformations

$$\mathcal{A} \longleftrightarrow \mathcal{A}'$$



$$\Phi(\mathcal{B} \circ \mathcal{A}, \mathcal{C}) = \Phi(\mathcal{B}, \mathcal{C} \circ \mathcal{A}')$$

Operational definition of *transposed*

For *symmetric* faithful state it is easy to check that the involution $\mathcal{A} \iff \mathcal{A}'$ satisfies the properties of the transposed:

1. $(\mathcal{A} + \mathcal{B})' = \mathcal{A}' + \mathcal{B}'$
2. $(\mathcal{A}')' = \mathcal{A}$,
3. $(\mathcal{A} \circ \mathcal{B})' = \mathcal{B}' \circ \mathcal{A}'$

Operational definition of *transposed*

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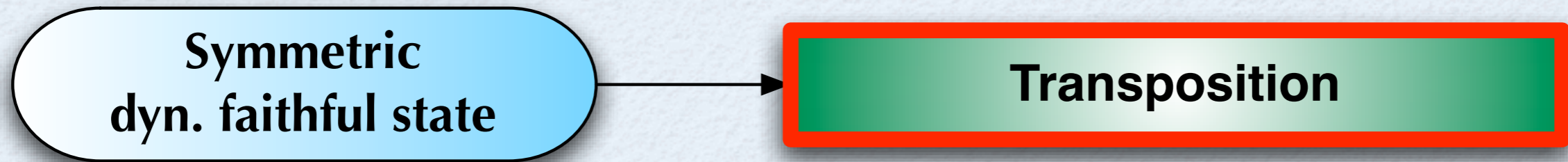
**Symmetric
dyn. faithful state**

Operational definition of *transposed*

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GNS construction for representing transformations

Extend ζ to an involution over transformations

$$\zeta(\mathcal{A}) =: \mathcal{A}^\zeta \in \zeta(\underline{\mathcal{A}})$$

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For *composition-preserving* ζ , i.e. $\zeta(\underline{\mathcal{B}} \circ \underline{\mathcal{A}}) = \underline{\mathcal{B}}^\zeta \circ \underline{\mathcal{A}}^\zeta$

ζ works as a **complex-conjugation** in the sense that

$\underline{\mathcal{A}}^\dagger := \zeta(\underline{\mathcal{A}}')$ works as an **adjoint**, namely

$$\Phi\langle \underline{\mathcal{C}}^\dagger \circ \underline{\mathcal{A}} | \underline{\mathcal{B}} \rangle_{\Phi} = \Phi\langle \underline{\mathcal{A}} | \underline{\mathcal{C}} \circ \underline{\mathcal{B}} \rangle_{\Phi}$$

GNS construction for representing transformations

Take complex linear combinations of generalized transformations and define $\zeta(c\mathcal{A}) = c^* \zeta(\mathcal{A})$ for $c \in \mathbb{C}$.

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c-generalized transformations: $\mathfrak{T}_{\mathbb{C}}$
c-generalized effects: $\mathfrak{B}_{\mathbb{C}}$

complex
Banach spaces

GNS construction for representing transformations

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GNS construction for representing transformations

Representations π_Φ of transformations $\mathcal{A} \in \mathcal{A}$ over effects \mathcal{A}/\mathcal{J}

$$\pi_\Phi(\mathcal{A})|\underline{\mathcal{B}}\rangle_\Phi \doteq |\underline{\mathcal{A} \circ \mathcal{B}}\rangle_\Phi$$

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The Born rule rewrites in the form of pairing:

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(transformations)

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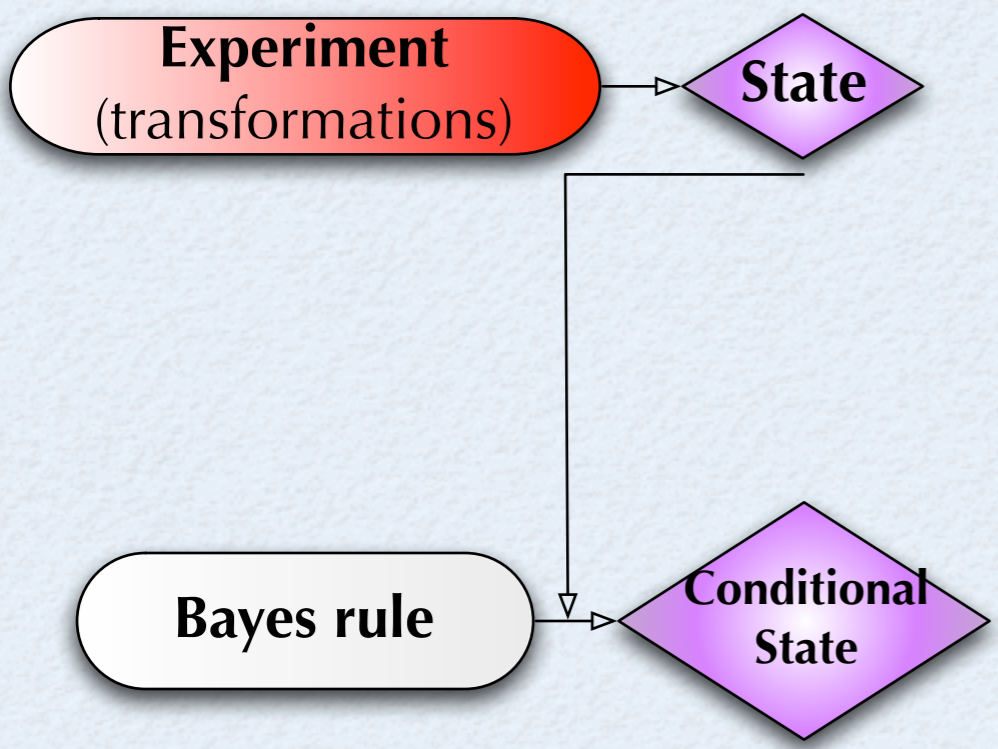


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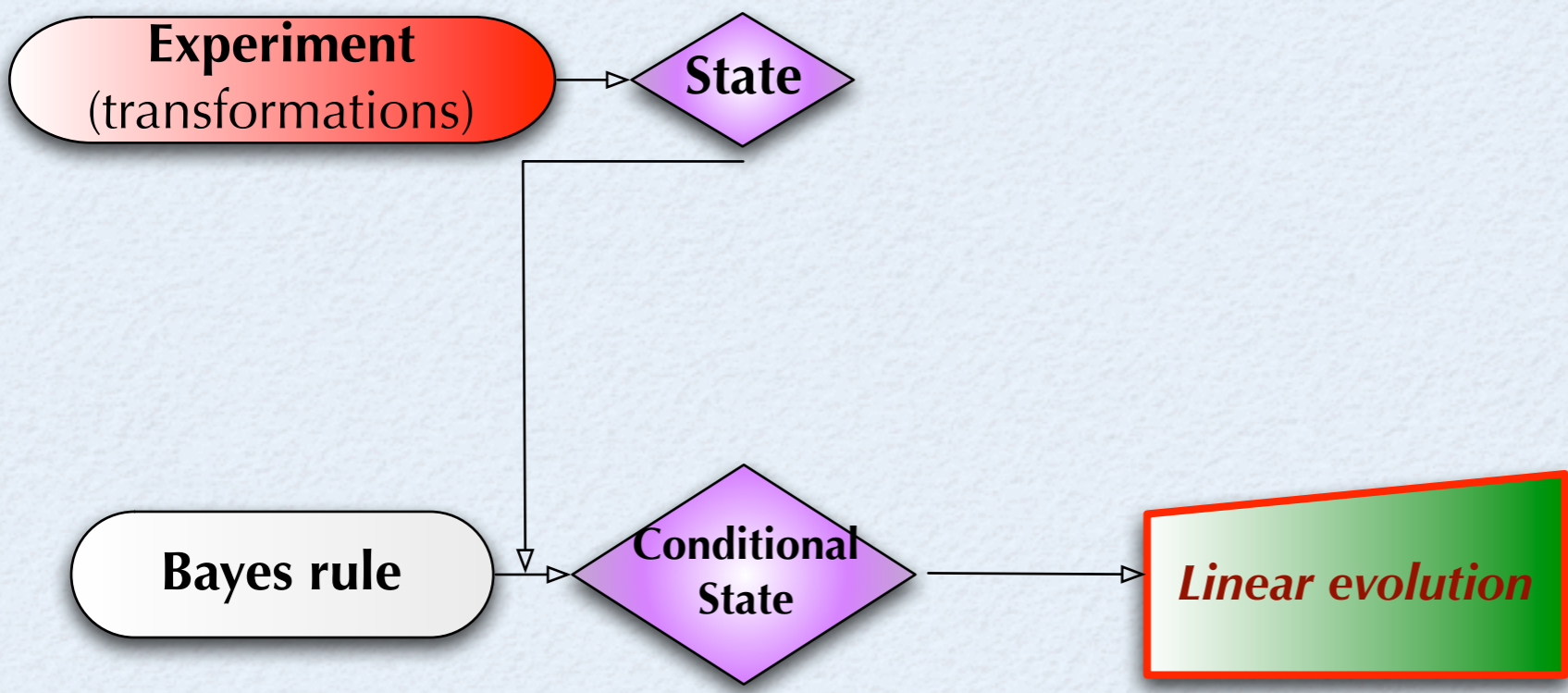
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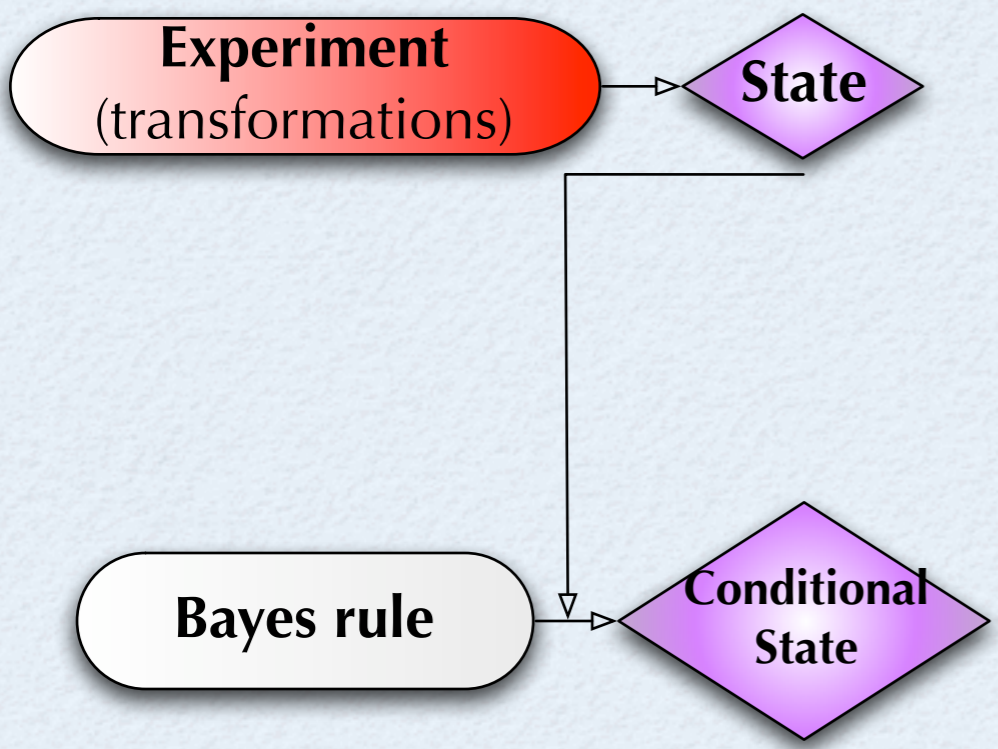
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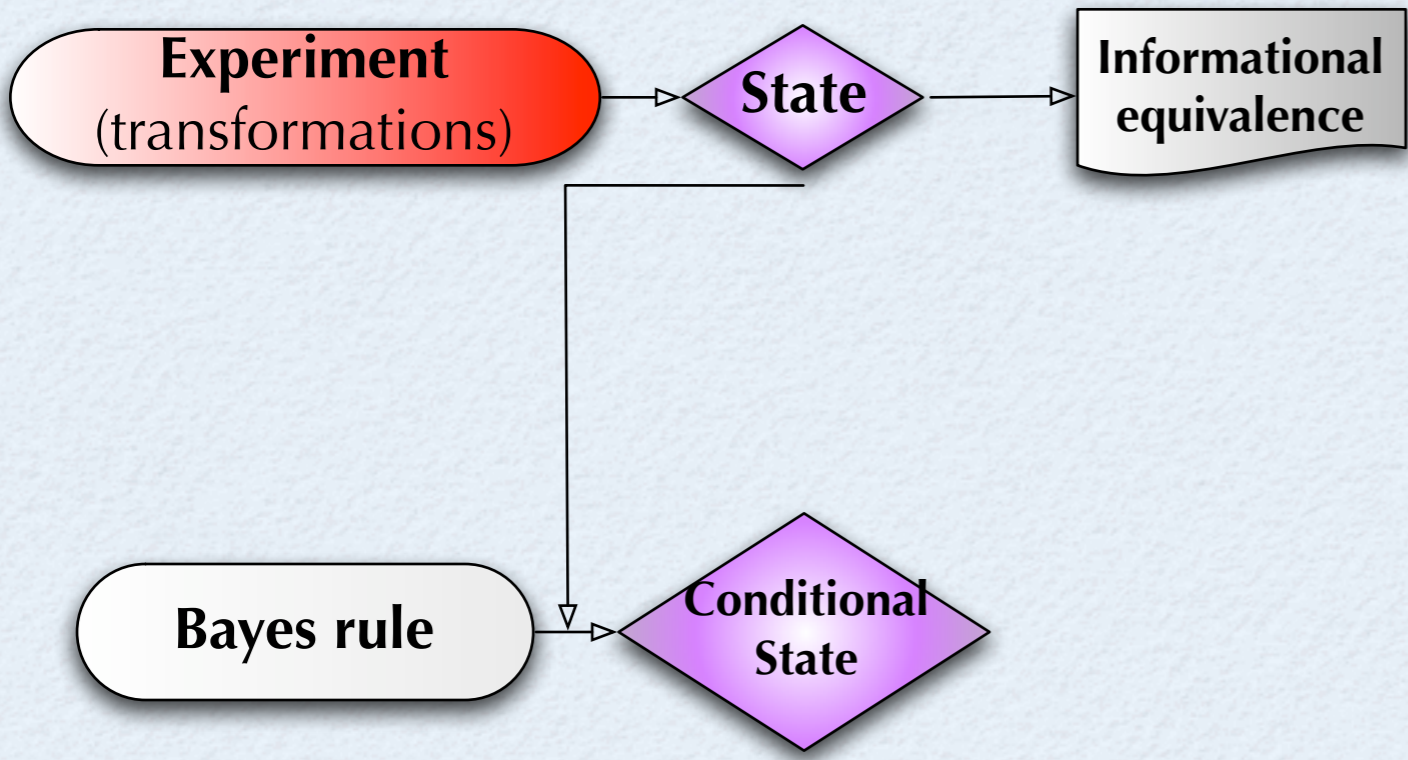
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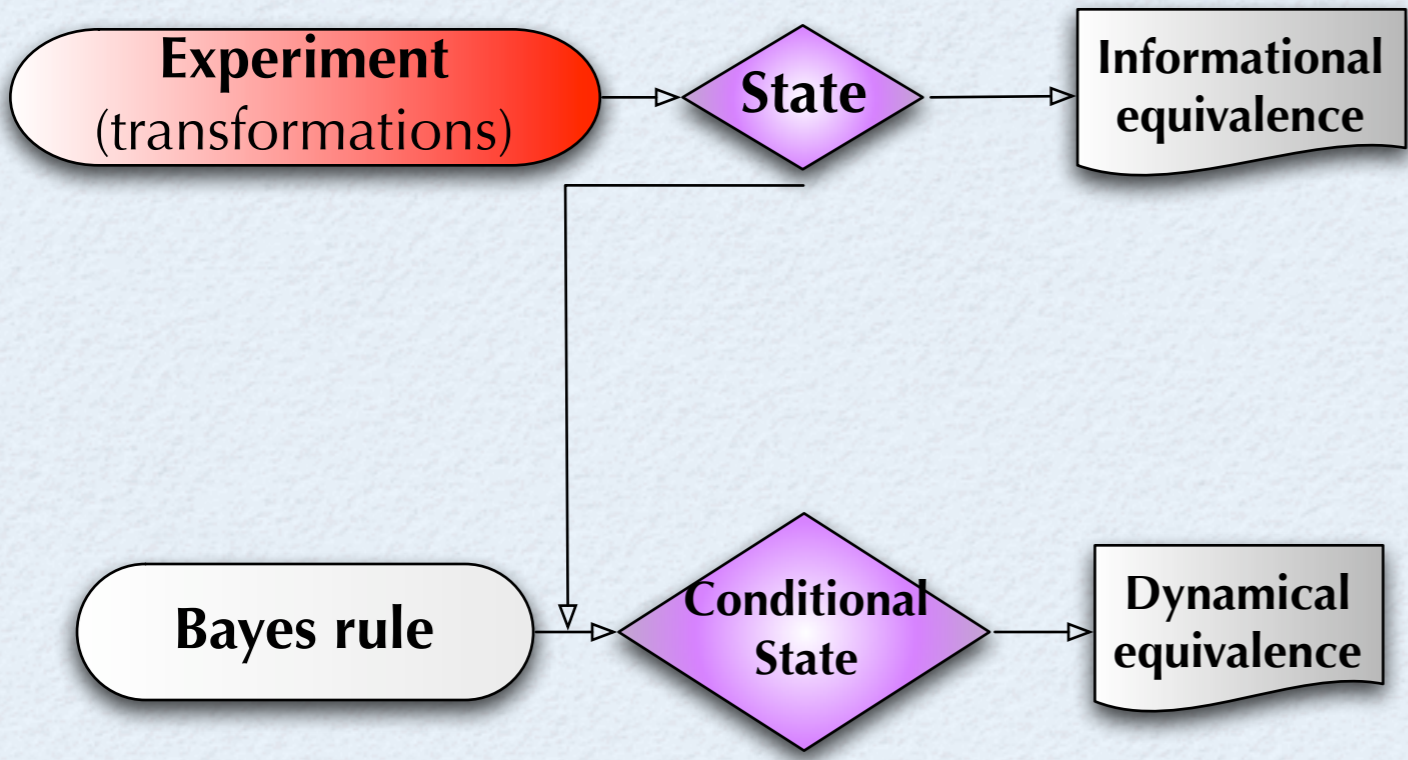
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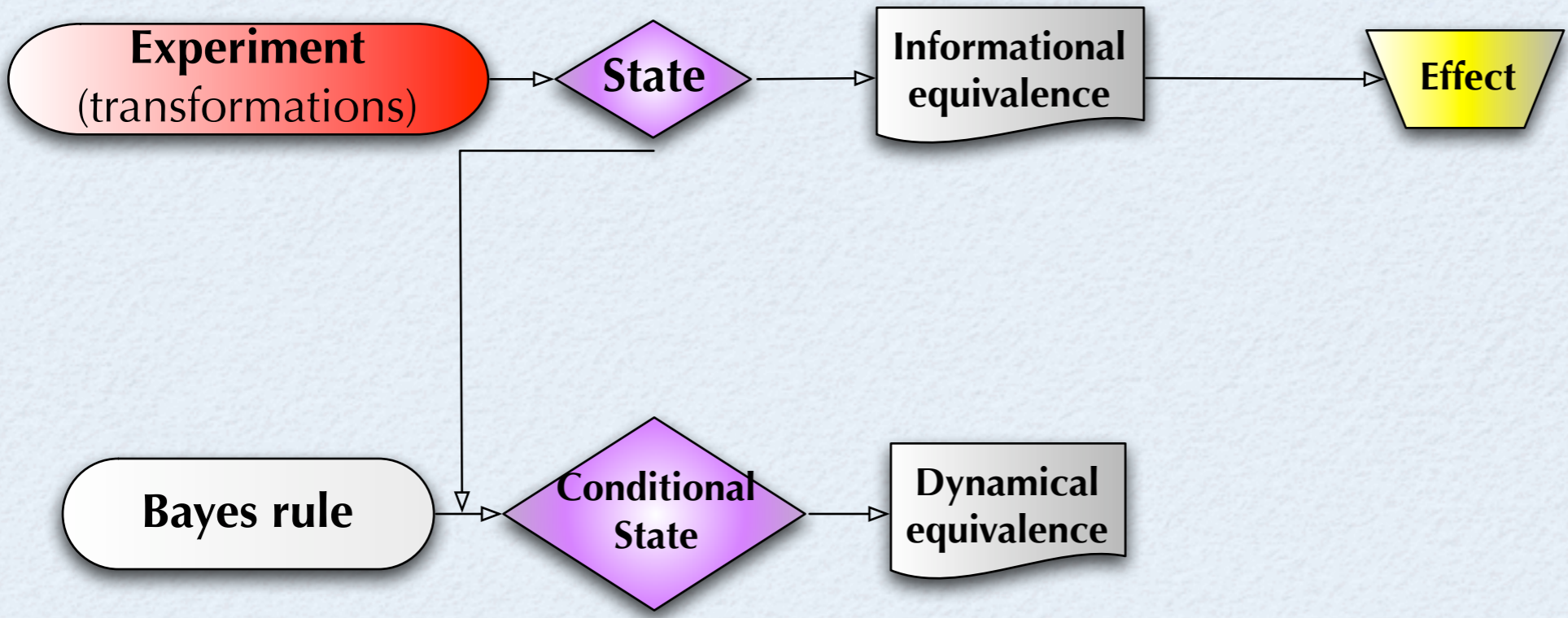


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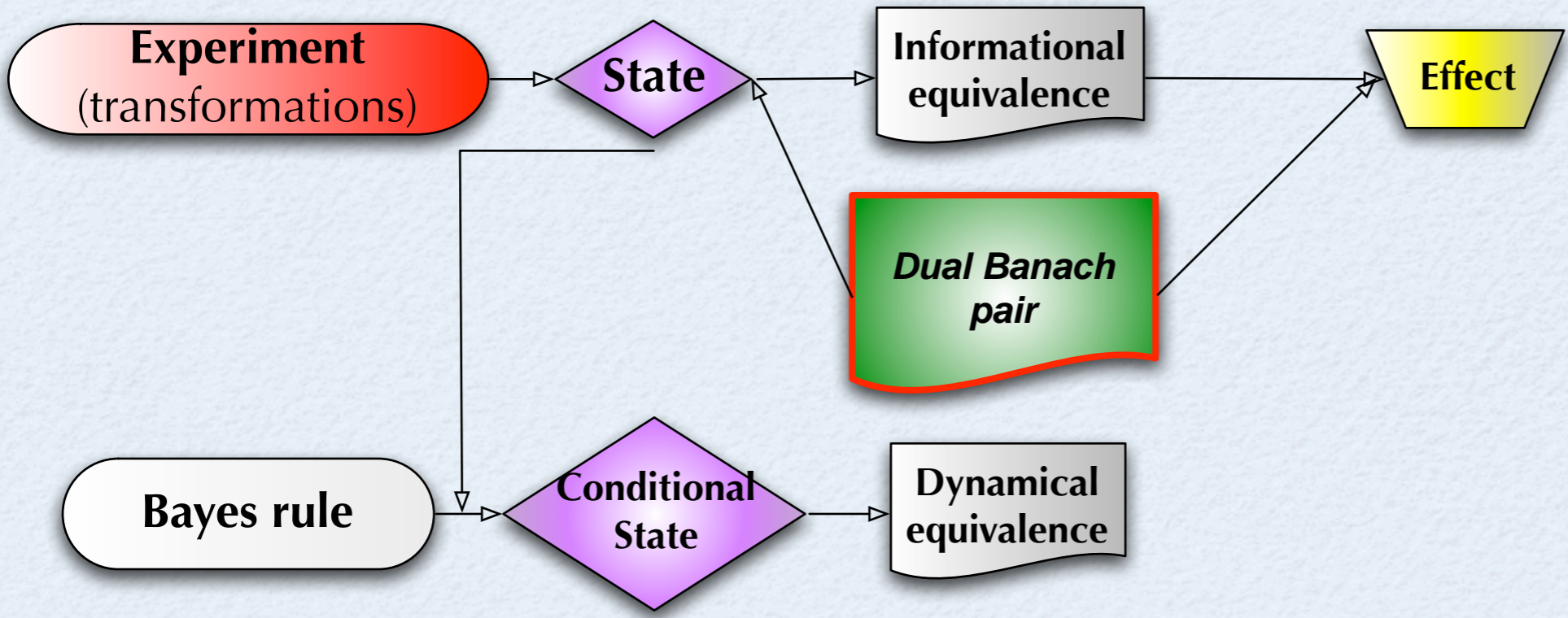
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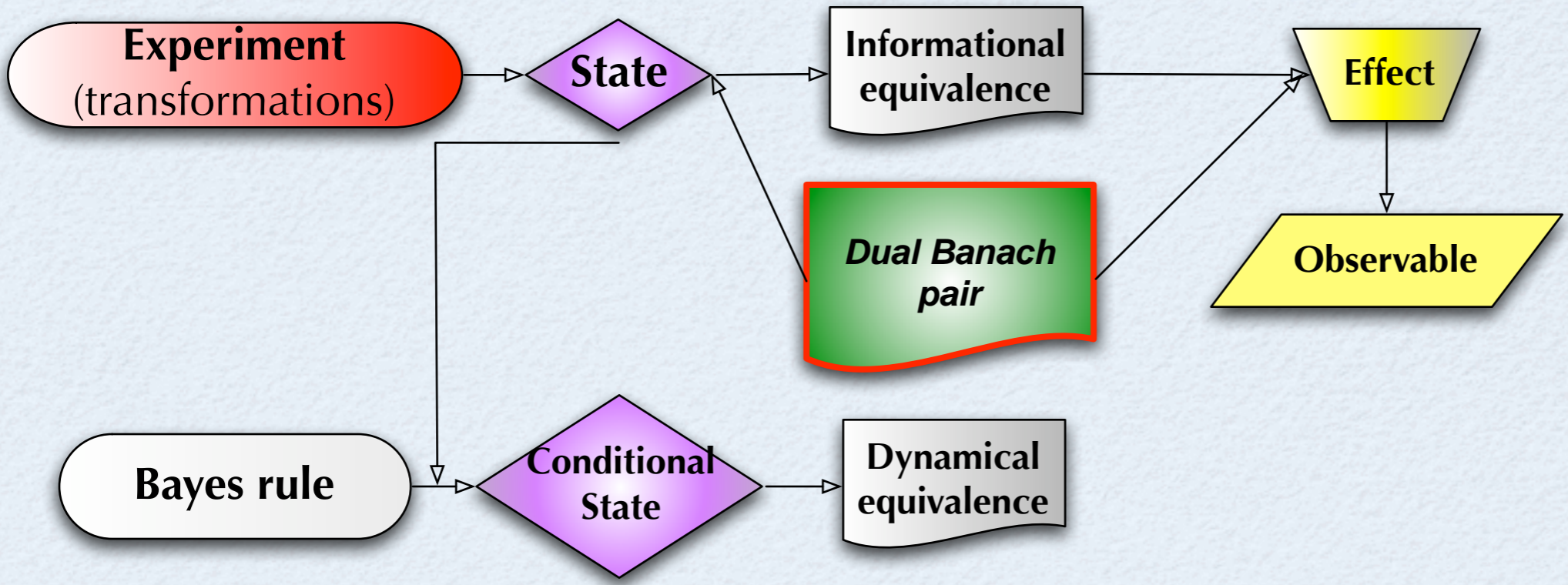
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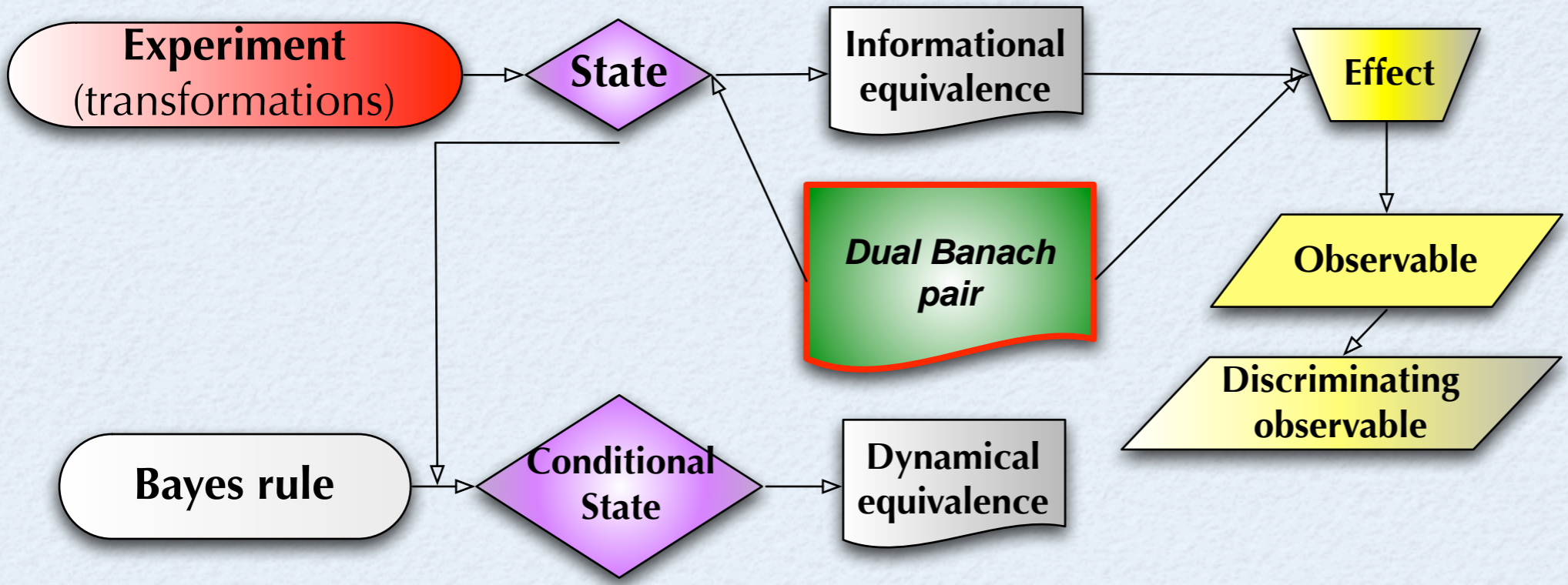
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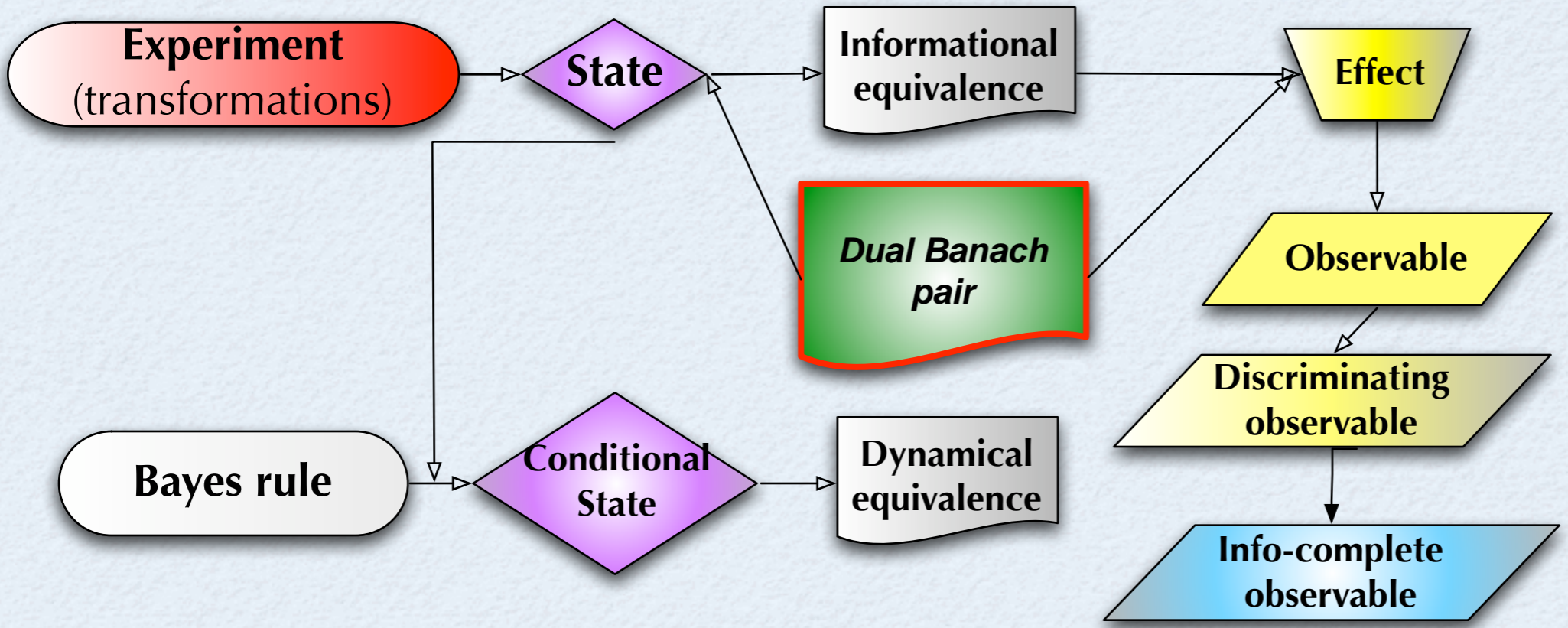
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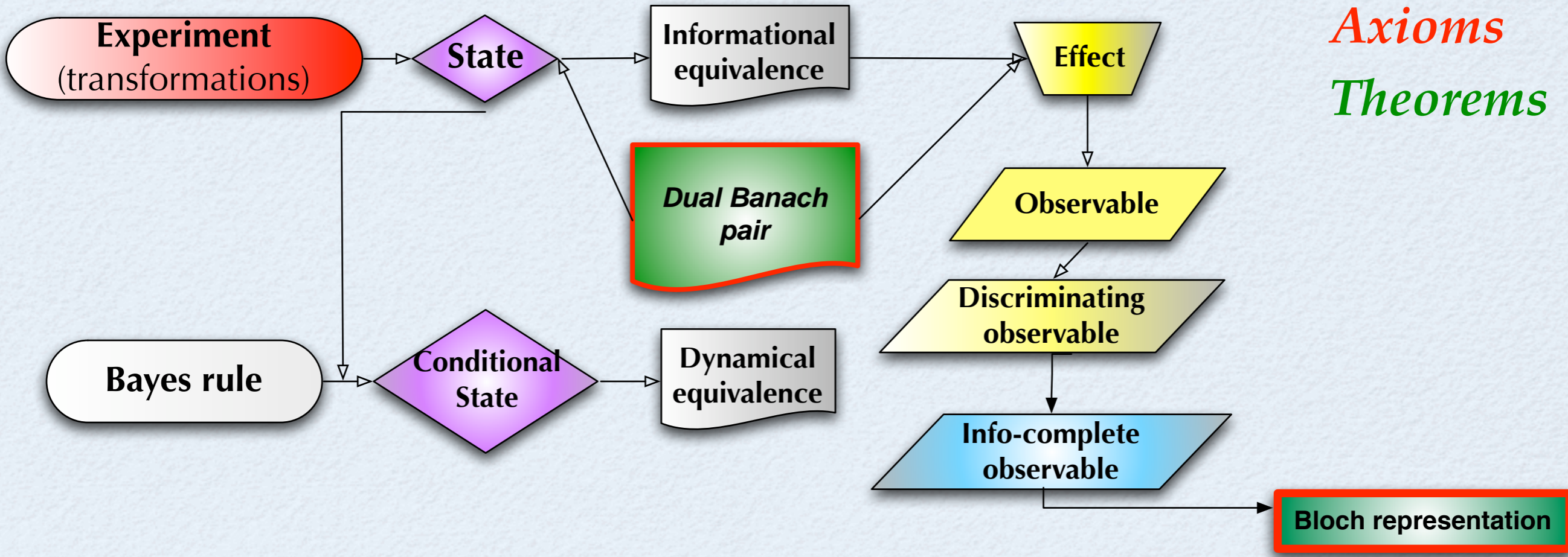
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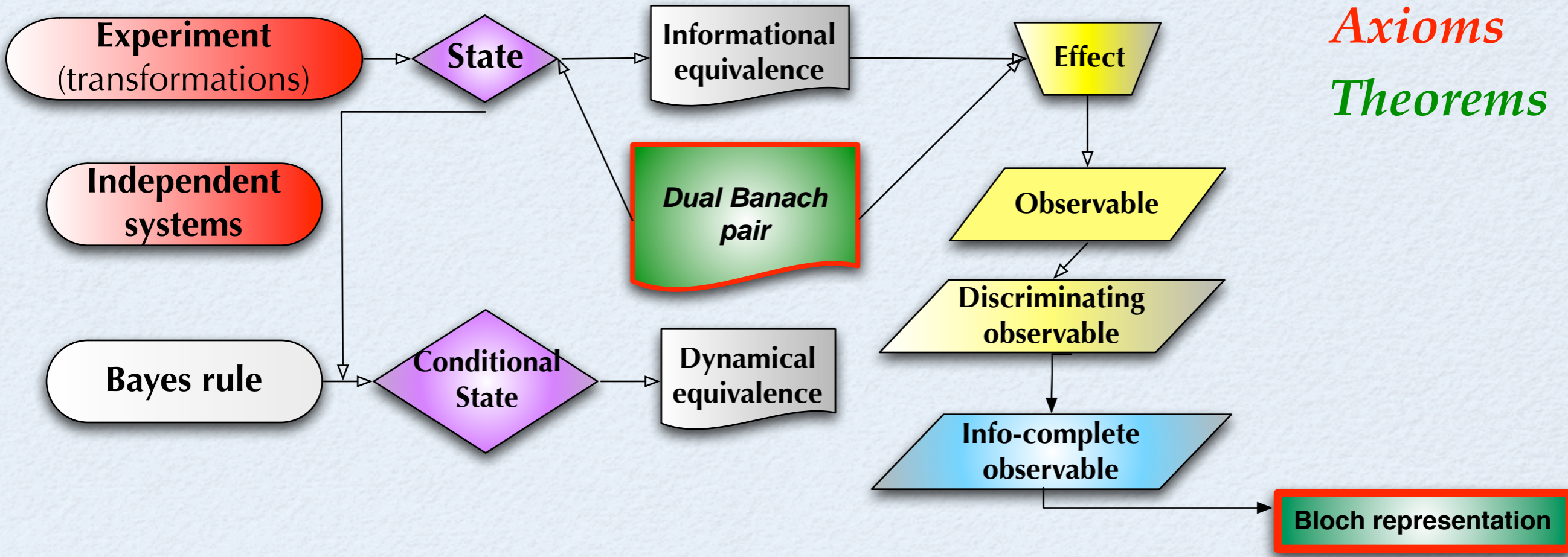
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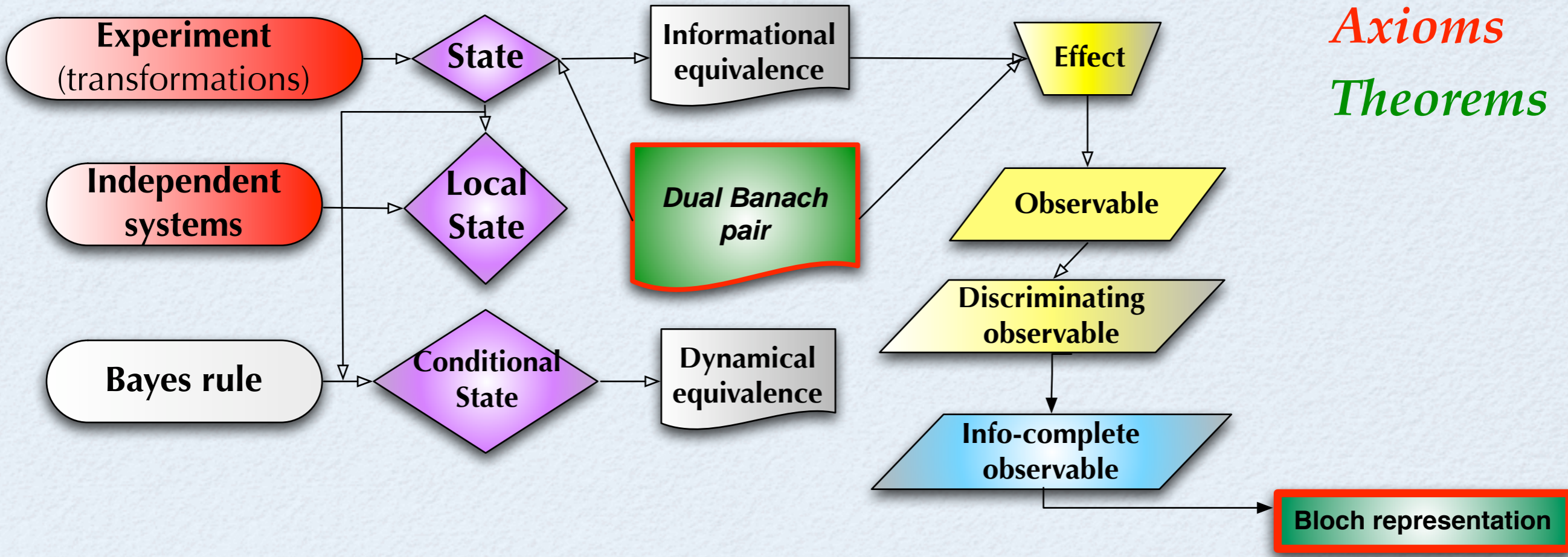
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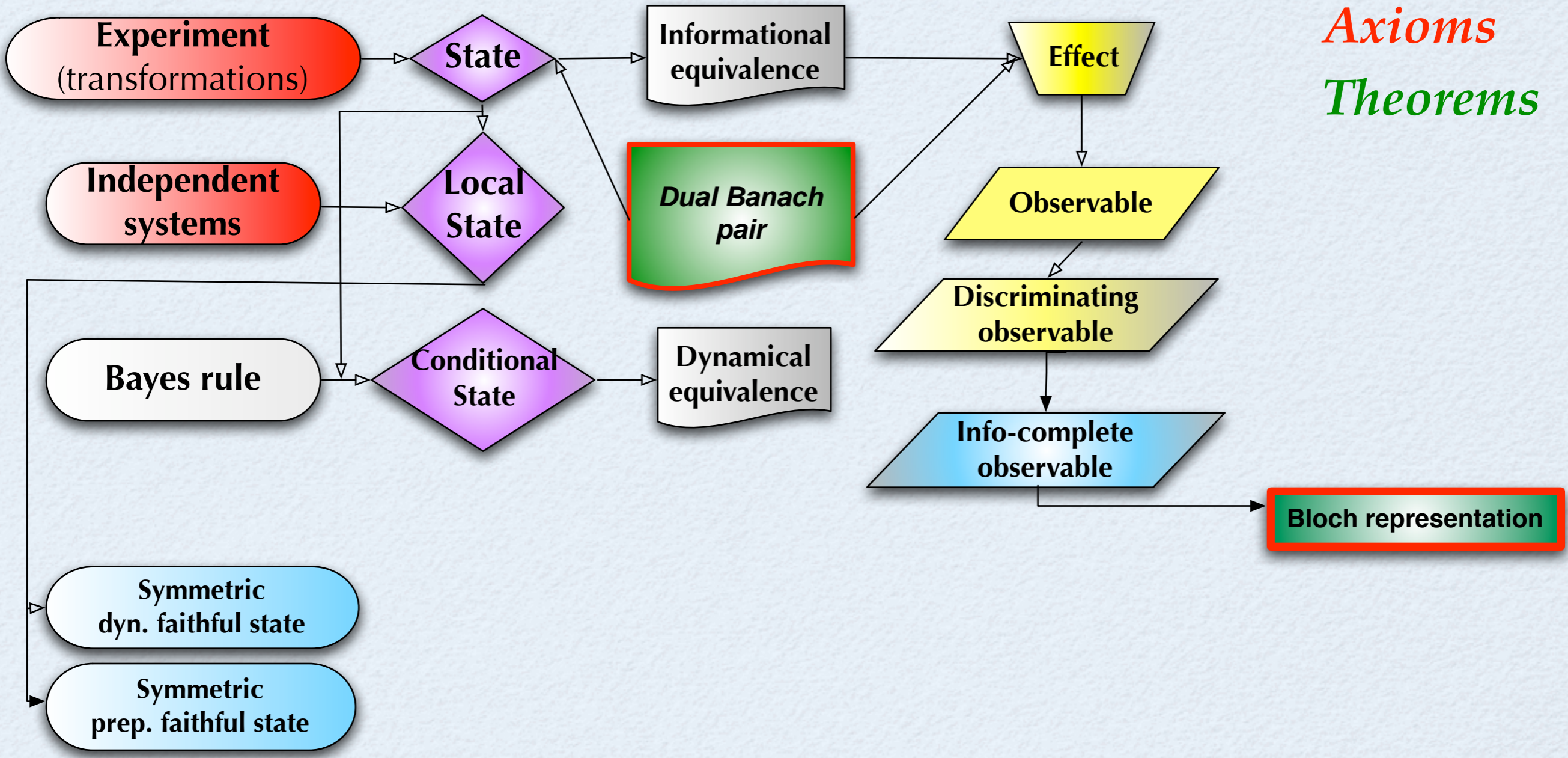
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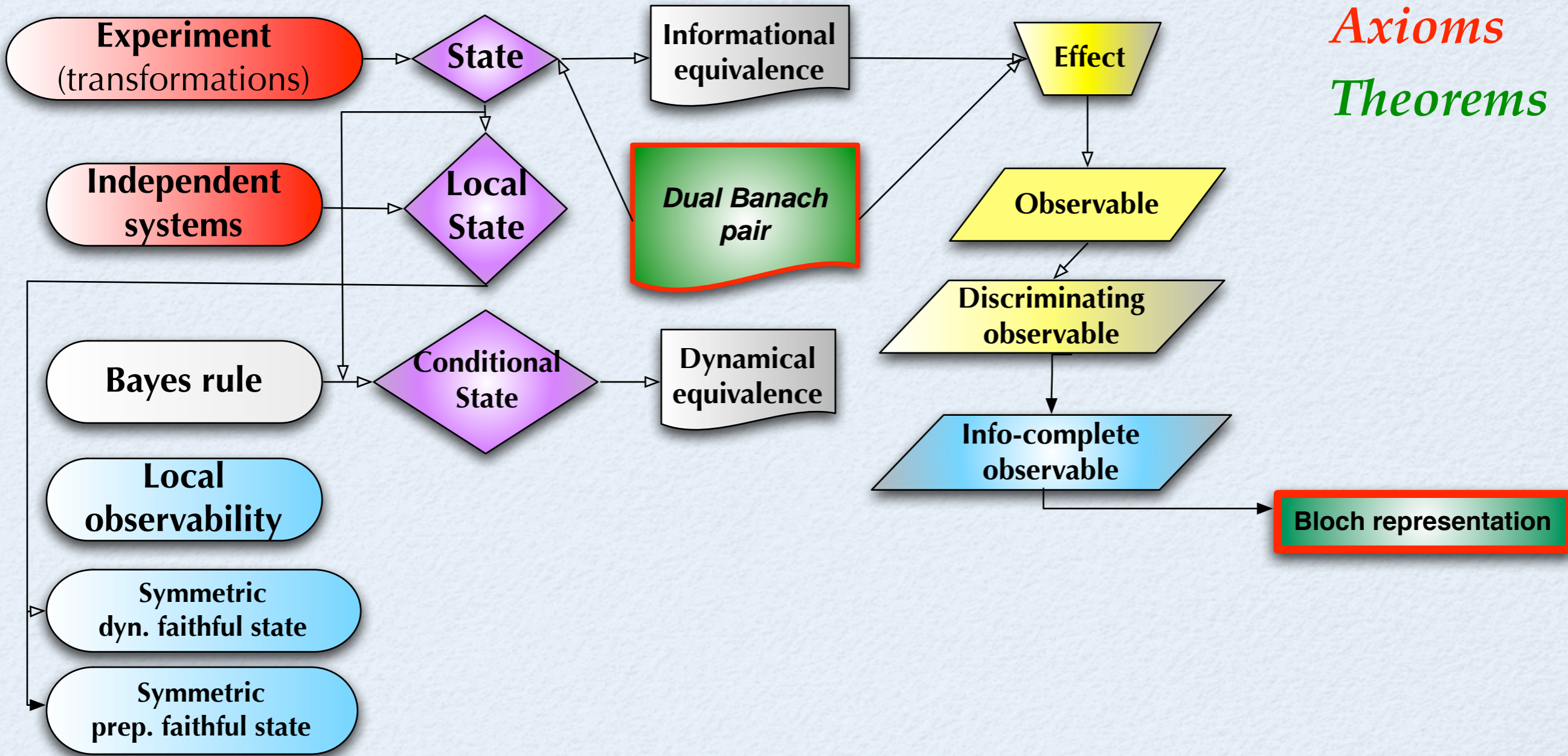
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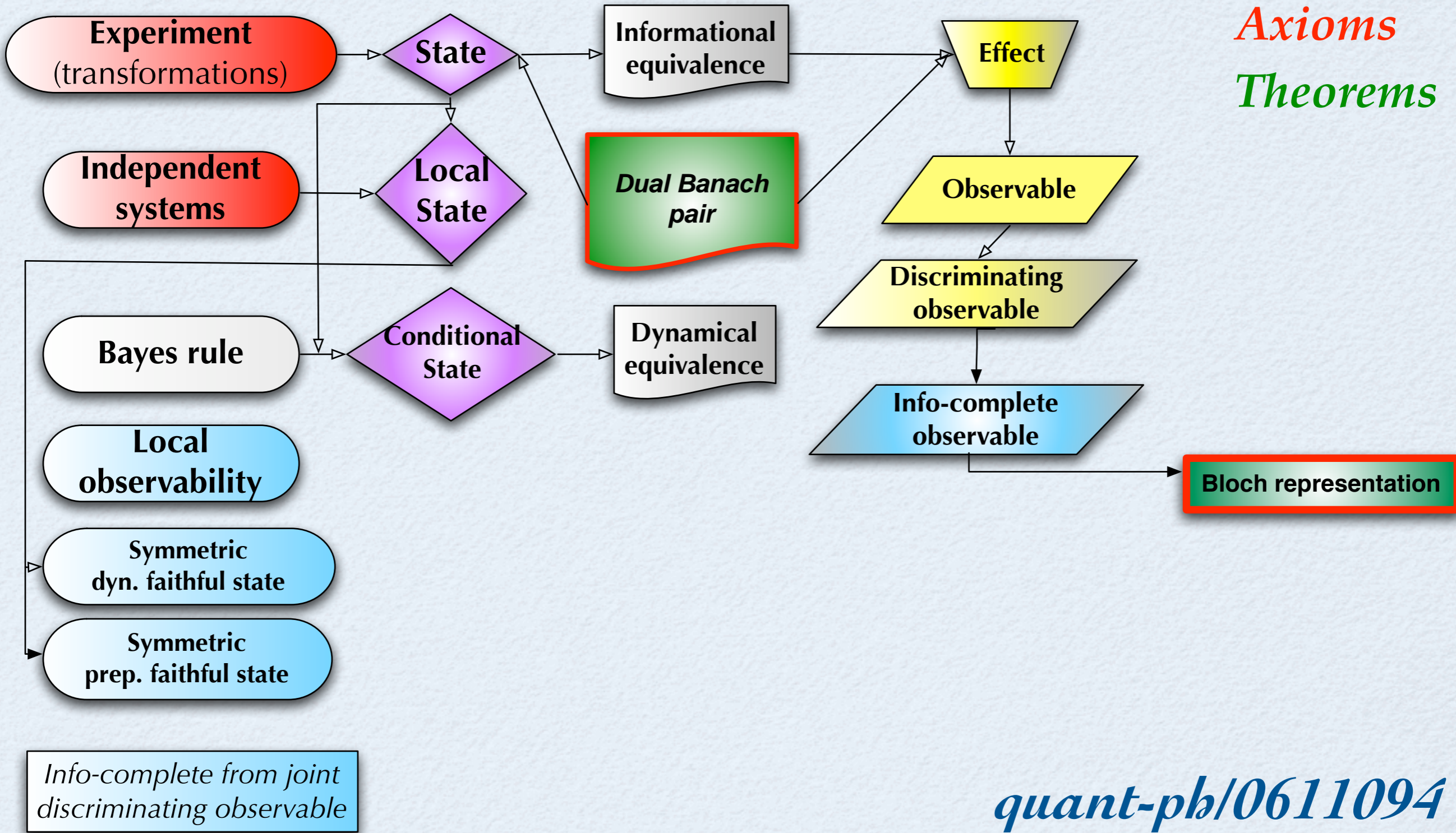
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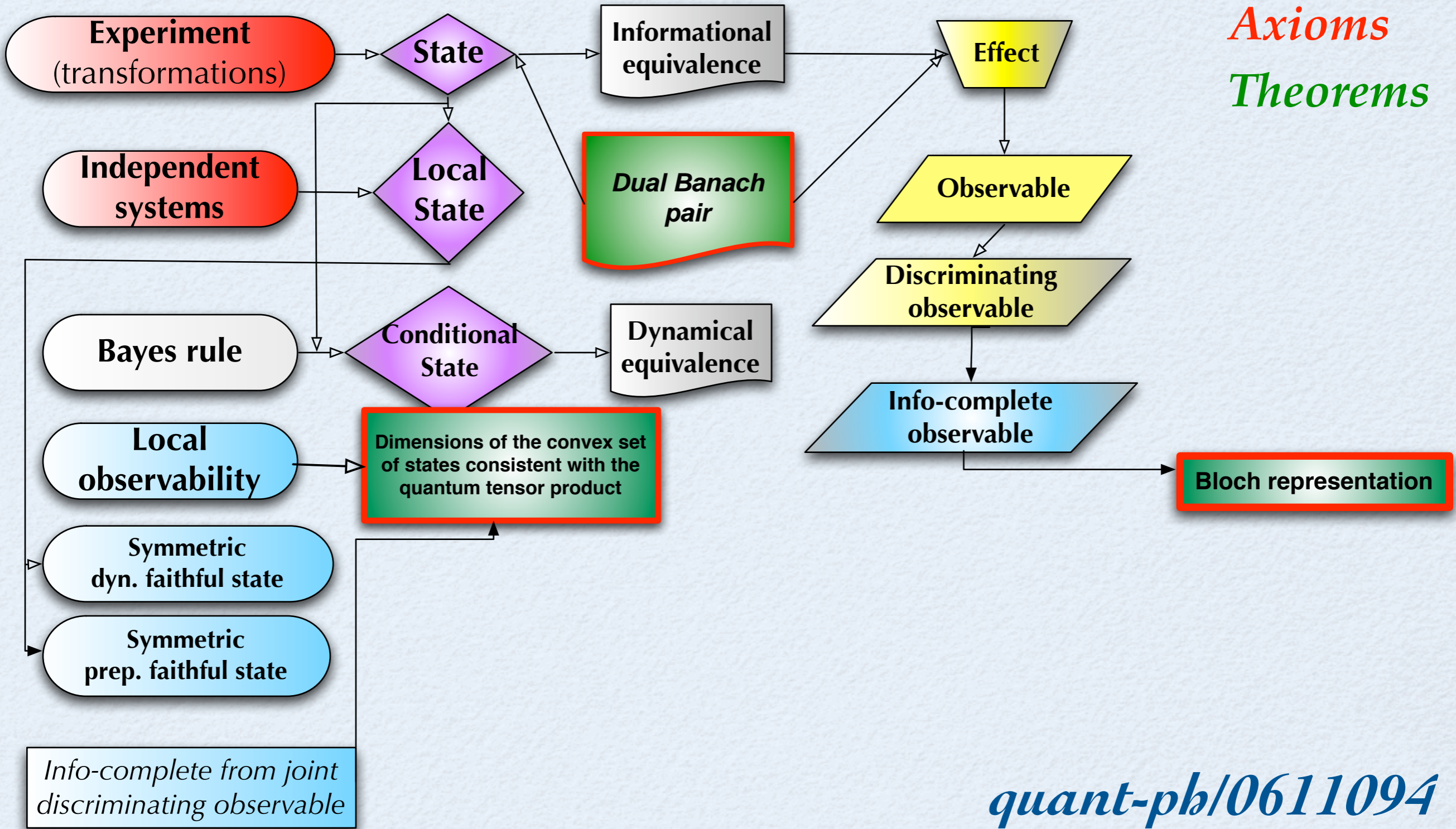
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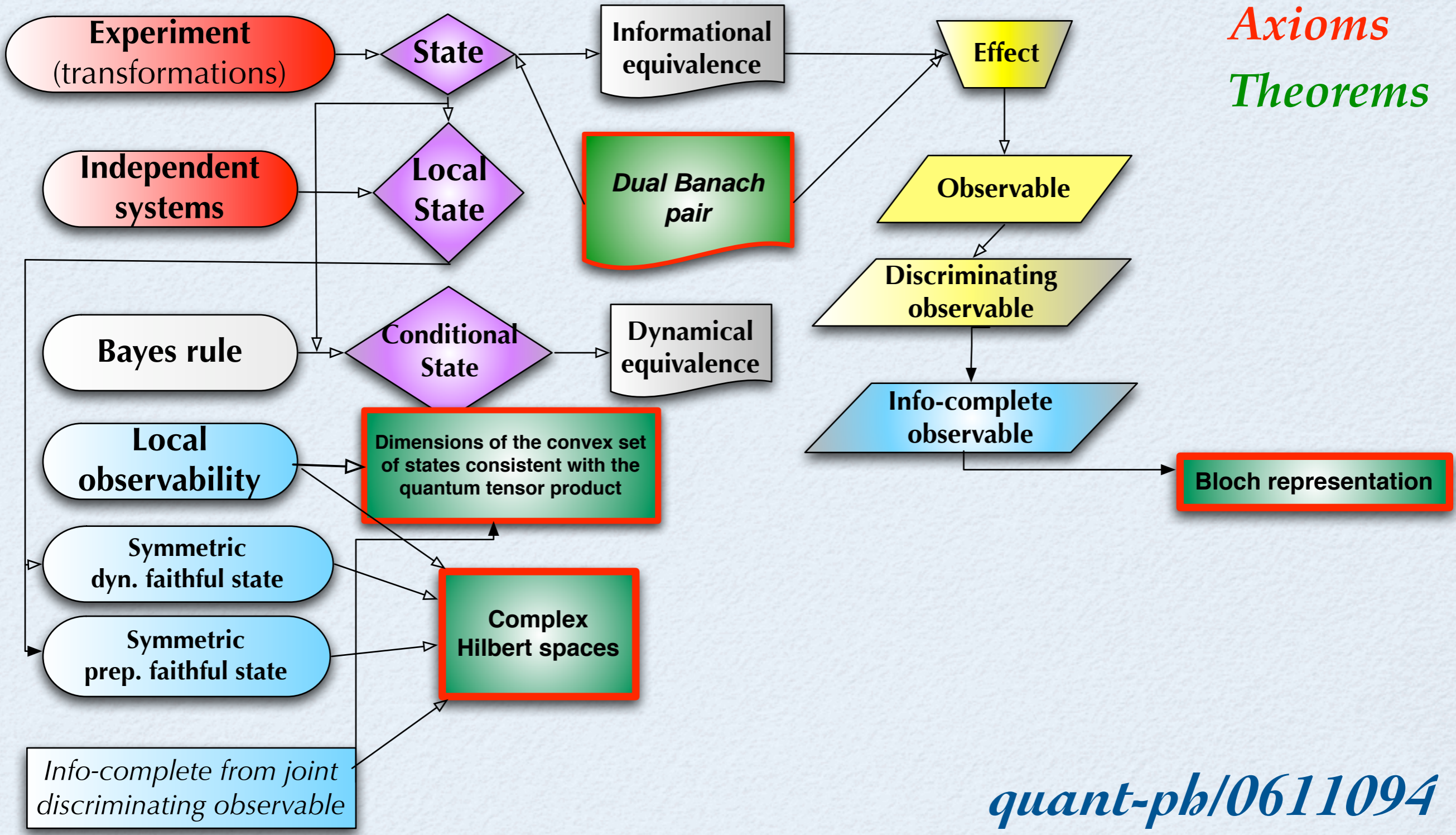
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